

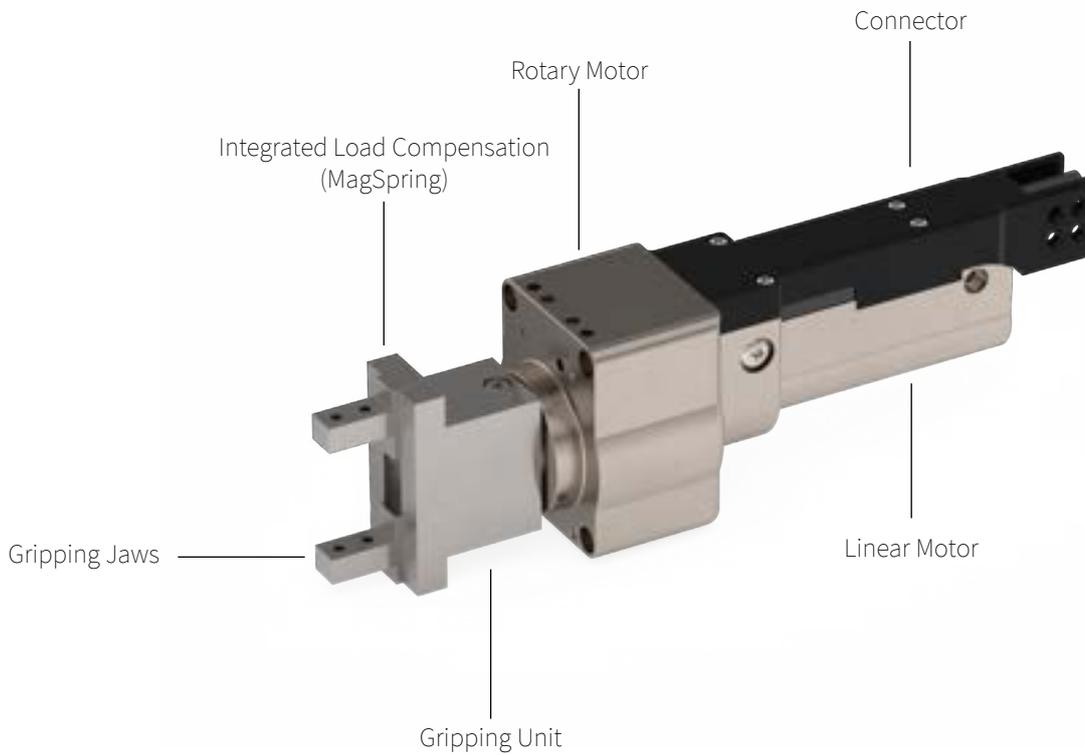
# GRIPPER MODULES GM51



- ✓ Electric servo rotary gripper with additional magnetic holding force
- ✓ Highly dynamic gripping, closing and opening times of less than 20 ms
- ✓ Smooth gripping thanks to freely programmable motion profiles
- ✓ Free finger positioning and force control via servo motor
- ✓ Maintains MagSpring in case of power failure, easy manual opening
- ✓ Clever design for neat cable routing directly with trailing chain connection
- ✓ Low power consumption in open and closed position
- ✓ Compatible with all common fieldbuses

## GRIPPER MODULES GM51

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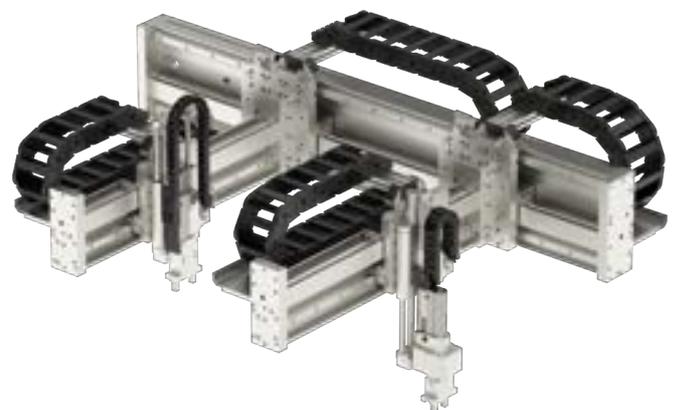
## Grippers GM51

The LinMot GM51 gripper is a highly dynamic solution for demanding applications. With extremely fast closing and opening times of less than 20 milliseconds, it enables efficient and reliable gripping. Freely programmable motion profiles can be used to make the gripping process particularly gentle, making it easier to handle sensitive objects. The gripper's servomotor enables precise finger positioning and force control, so gripping can be customised.

The GM51 has an integrated rotary motor with endless rotation. This makes the gripper particularly suitable for dynamic positioning, assembly and screwing tasks, and the accuracy of the absolute encoder provides high precision angular positioning. In addition, the position of the gripper fingers is monitored by the linear motor, eliminating the need for external sensors and cables that interfere with rotation. The GM51 has an integrated adapter for drag chains and cables.

## Combination with guides and modules

The combination of the GM51 parallel gripper with the FM01 and EM01 guides and the DM01 and DM03 modules enables complete pick-and-place and pick-rotate-and-place applications thanks to the simple coupling and modular design of the LinMot components. The GM51 is also available with passive load compensation (MagSpring). A combination that offers maximum precision, speed and safety even under the most demanding conditions.



## PERFORMANCE DATA GM51-23SX80F-XP-K\_35-18\_E50X0.8(\_MS03)



Performance Data Gripper Module GM51-23SX80F-XP-K\_35-18\_E50x0.8(\_MS03)

Performance Data Gripper Module GM51-23SX80F-XP-K_35-18_E50x0.8(_MS03)			
<b>Stroke</b>			
Max. Opening/Closing Stroke Range	mm (in)	18	(0.71)
<b>Force</b>			
Max. Clamping Force (<0.75 s) with MagSpring / without MagSpring	N (lbf)	56 / 45	(12.59 / 10.12)
Max. Torque Rotary Motor	Nm (lbf)	1.03	(9.15)
Continuous Torque Rotary Motor	Nm (lbf)	0.32	(2.83)
Max. Continuous Clamping Force Closing Direction with MagSpring / without MagSpring	N (lbf)	19 / 9	(4.27 / 2.02)
Max. Continuous Clamping Force Opening Direction with MagSpring / without MagSpring	N (lbf)	7 / 7	(1.57 / 1.57)
Max. Continuous Clamping Force Through the MagSpring (no power)	N (lbf)	11	(2.47)
<b>Velocity</b>			
Minimum Opening/Closing Time	s	0.02	
Max. Rotary Speed	rpm	3500*	
<b>Position Detection</b>			
Position Resolution	mm (in)	0.002	(0.00008)
Repeatability Gripper Motor	mm (in)	±0.05	(±0.002)
Repeatability Rotary Motor	° °	±0.05	(±0.002)
<b>Electrical Data</b>			
Max. Current Gripper Motor @ 48 / 72VDC	A <sub>pk</sub>	7.4	
Max. Current Rotary Motor @ 48 / 72VDC	A <sub>pk</sub>	20.8	
<b>Mechanical Data</b>			
Gripper Width	mm (in)	70	(2.76)
Gripper Length	mm (in)	67.6	(2.66)
Gripper Height	mm (in)	244.8	(9.64)
Gripper Mass	g (lb)	1100	(2.43)
Ambient Temperature	°C	-10 bis 60	
IP Protection Class		IP 30	
<b>Drive</b>			
Power Supply Drive	VDC	24-72	
Number of Required Drives	Stk.	2	
Communication Protocols		PROFINET, PROFIdrive, EtherNet/IP, EtherCAT, CANopen, sercos, Ethernet Powerlink	

\*Theoretical no-load rotation speeds at rated voltage  $U_n$ .

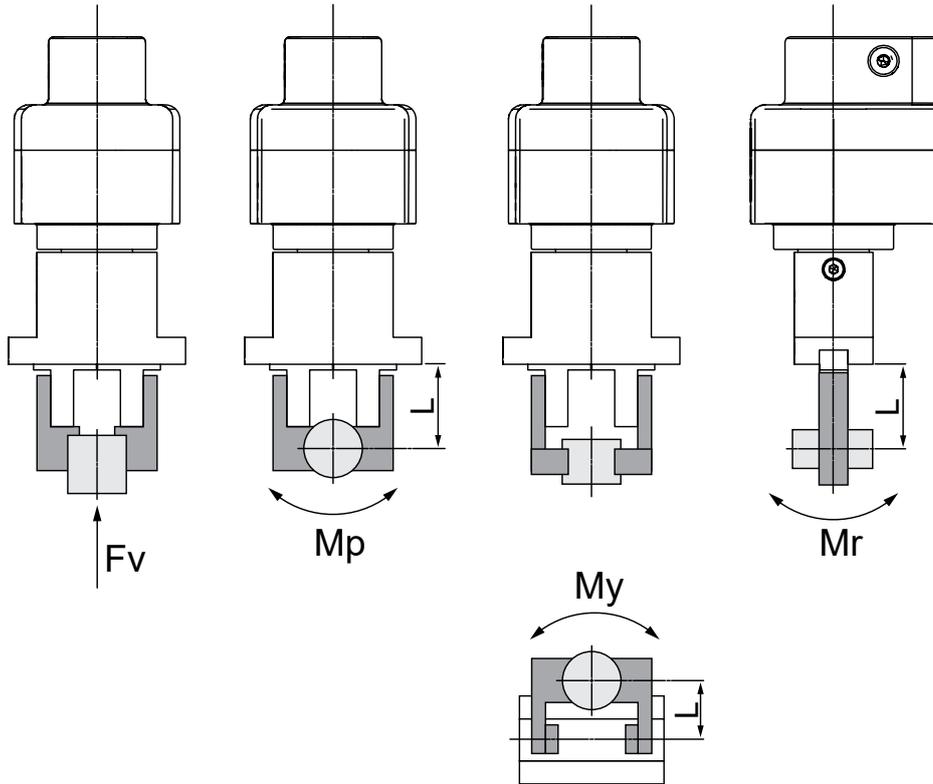
**PERFORMANCE DATA GM51-37SX60-XP-N\_48-26\_E70X18-N(\_MS03)**



Performance Data Gripper Module GM51-37SX60-XP-N_48-26_E70x18-N(_MS03)				
<b>Stroke</b>				
Max. Opening/Closing Stroke Range	mm (in)		22 (0.87)	
<b>Force</b>				
Max. Clamping Force (<0.75 s)	N (lbf)		128 / 97 (28.78 / 21.81)	
Max. Torque Rotary Motor	Nm (lbf)		3.92 (34.69)	
Continuous Torque Rotary Motor	Nm (lbf)		1.21 (10.71)	
Max. Continuous Clamping Force Closing Direction	N (lbf)		42 / 12 (9.44 / 2.70)	
Max. Continuous Clamping Force Opening Direction	N (lbf)		10 / 10 (2.25 / 2.25)	
Max. Continuous Clamping Force Through the MagSpring (no power)	N (lbf)		31 (6.97)	
<b>Velocity</b>				
Minimum Opening/Closing Time	s		0.03	
Max. Rotary Speed	rpm		3000*	
<b>Position Detection</b>				
Position Resolution	mm (in)		0.005 (0.0002)	
Repeatability Gripper Motor	mm (in)		±0.05 (±0.002)	
Repeatability Rotary Motor	° °		±0.05 (±0.002)	
<b>Electrical Data</b>				
Max. Current Gripper Motor @ 48 / 72VDC	$A_{pk}$		9.4	
Max. Current Rotary Motor @ 48 / 72VDC	$A_{pk}$		24.6	
<b>Mechanical Data</b>				
Gripper Width	mm (in)		103 (4.06)	
Gripper Length	mm (in)		104.8 (4.13)	
Gripper Height	mm (in)		294.2 (11.58)	
Gripper Mass	g (lb)		2770 (6.11)	
Ambient Temperature	°C		-10 bis 60	
IP Protection Class			IP 30	
<b>Drive</b>				
Power Supply Drive	VDC		24-72	
Number of Required Drives	Stk.		2	
Communication Protocols			PROFINET, PROFIdrive, EtherNet/IP, EtherCAT, CANopen, sercos, Ethernet Powerlink	

\*Theoretical no-load rotation speeds at rated voltage  $U_r$ .

**CALCULATION OF THE LOAD MOMENTS**



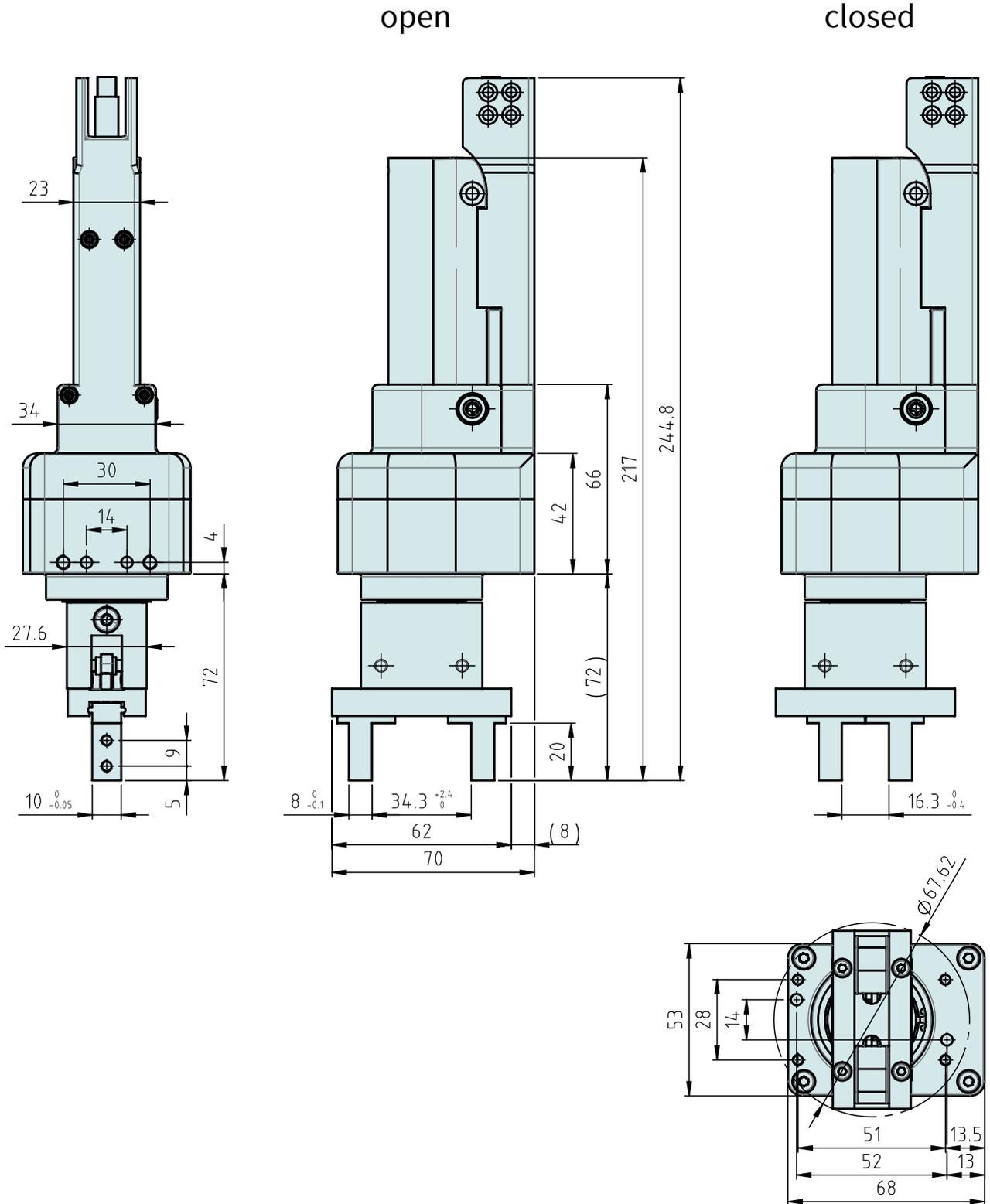
L: Distance to the point at which the load is applied (mm).

Model	Allowable vertical load Fv (N)	Maximum allowable moment		
		Pitch moment Mp (Nm)	Yaw moment My (Nm)	Roll moment Mr (Nm)
<b>GM51-23Sx80F-XP-K_35-18_E50x0.8(_MS03)</b>	147	1.32	1.32	2.65
<b>GM51-37Sx60-XP-N_48-26_E70x18-N(_MS03)</b>	343	3.0	3.0	6.0

Values for load and moment in the table indicate static values.

Calculation of allowable external force (when moment load is applied)	Calculation example
$\text{Allowable load } F \text{ (N)} = \frac{M \text{ (maximum allowable moment) (N} \cdot \text{m)}}{L \times \frac{10^{-3}}{*}}$ <p>(*Unit conversion constant)</p>	<p>When a static load of = 10N is operating, which applies pitch moment to point L = 30mm from the GM51-23 guide.</p> $\text{Allowable load } F \text{ (N)} = \frac{1.32}{30 \times 10^{-3}} = 44.0 \text{ (N)}$ <p><b>Load f = 10 (N) &lt; 44.0 (N)</b> Therefore, it can be used.</p>

**GRIPPER GM51-23SX80F-XP-K\_35-18\_E50X0.8(\_MS03)**

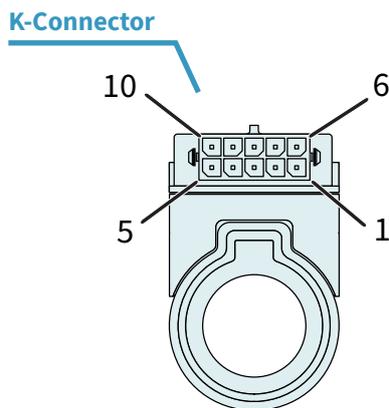


Dimensions in mm

Item	Description	Item-No.
GM51-23Sx80F-XP-K_35-18_E50x0.8	Gripper Module, max. stroke 18 mm, max. Force 45 N	<a href="#">0150-6599</a>
GM51-23Sx80F-XP-K_35-18_E50x0.8_MS03	Gripper Module with MagSpring, max. stroke 18 mm, max. force 56 N	<a href="#">0150-6302</a>

**CONNECTOR GM51-23 LINEAR MOTOR**

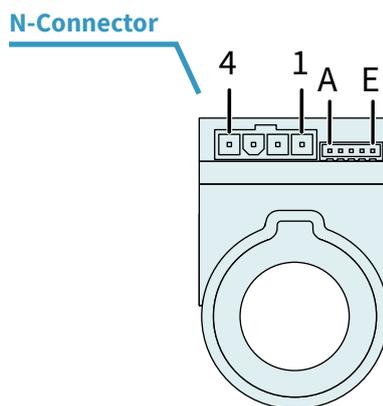
Motor connector wiring		Wire color motor cable
Pin 1	Phase 1+	red
Pin 2	Phase 2+	blue
Pin 3	n.c.	n.c.
Pin 4	Phase 1-	pink
Pin 5	Phase 2-	grey
Pin 6	Sensor Sin	yellow
Pin 7	Sensor Cos	green
Pin 8	GND	brown
Pin 9	+5V	white
Pin 10	Temp sensor	black
	Housing	Shield



View: motor connector, plug side

**CONNECTOR GM51-37 ROTARY MOTOR**

Motor connector wiring	N-Connector	Wire color motor cable
Phase 1+	Pin 4	red
Phase 1-	Pin 3	pink
Phase 2+	Pin 2	blue
Phase 2-	Pin 1	grey
+5V	Pin A	white
GND	Pin B	Inner Shield
Sensor Sin	Pin C	yellow
Sensor Cos	Pin D	green
Temp Sensor	Pin E	black
Housing		Outer Shield

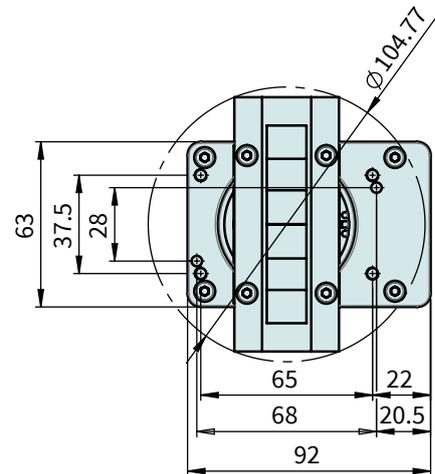
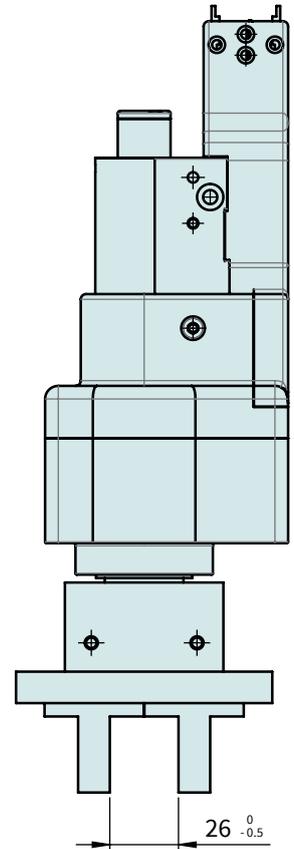
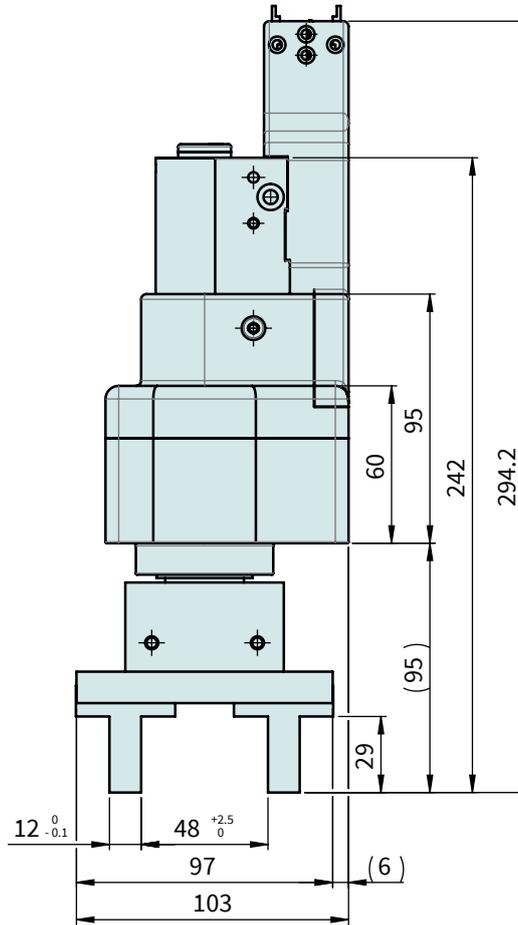
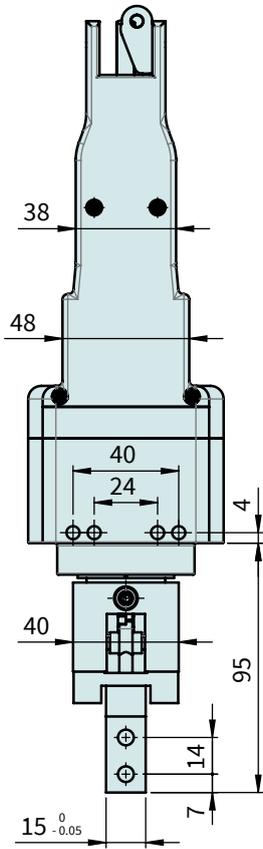


View: motor connector, plug side

**GRIPPER GM51-37SX60-XP-N\_48-26\_E70X18-N(\_MS03)**

open

closed



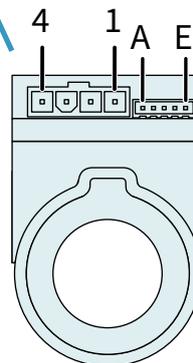
Dimensions in mm

Item	Description	Item-No.
<b>GM51-37Sx60-XP-N_48-26_E70x18-N</b>	Gripper Module, max. stroke 22 mm, max. Force 97 N	<a href="#">0150-6596</a>
<b>GM51-37Sx60-XP-N_48-26_E70x18-N_MS03</b>	Gripper Module with MagSpring, max. stroke 22 mm, max. force 128 N	<a href="#">0150-6255</a>

**CONNECTOR GM51-37 LINEAR MOTOR / ROTARY MOTOR**

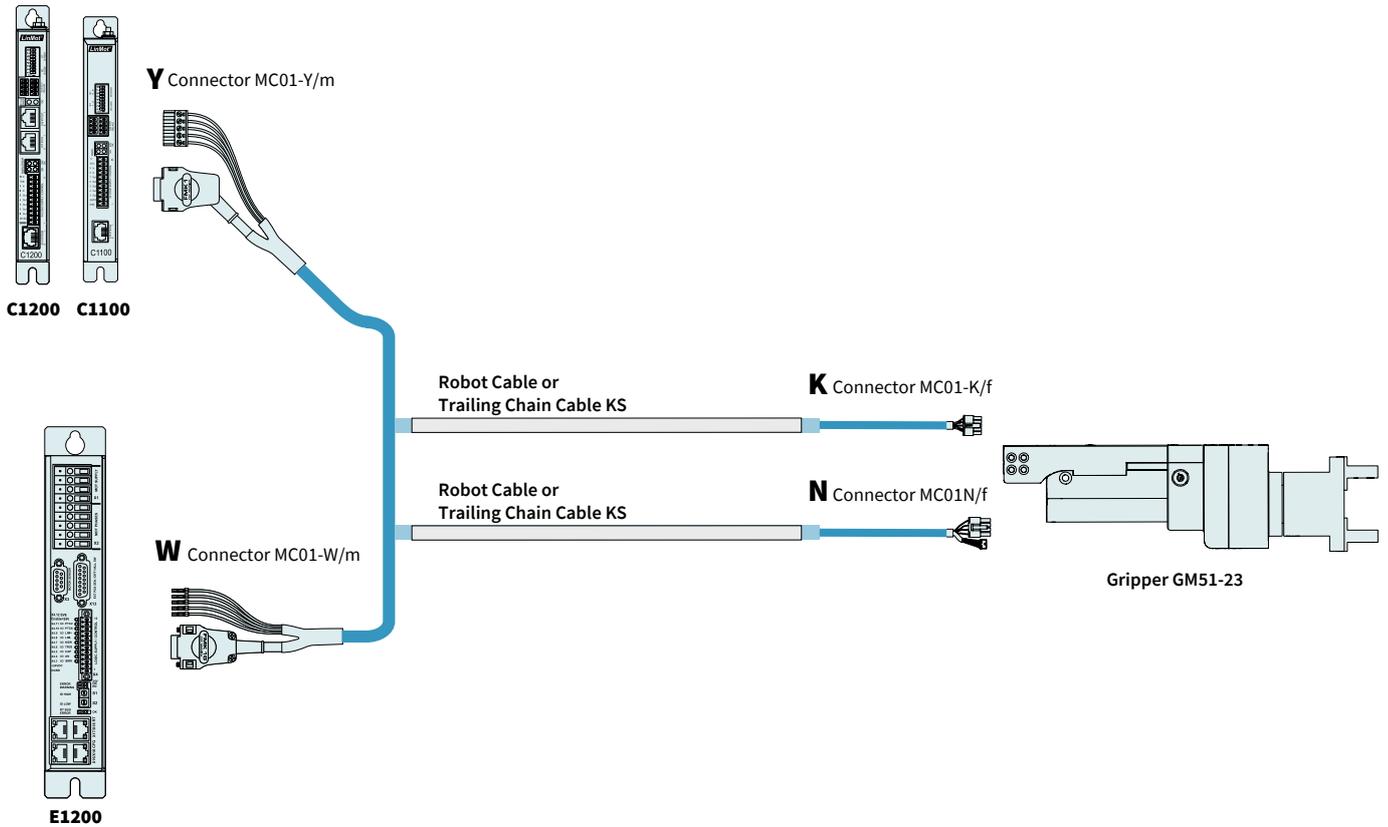
Motor connector wiring	N-Connector	Wire color motor cable
Phase 1+	Pin 4	red
Phase 1-	Pin 3	pink
Phase 2+	Pin 2	blue
Phase 2-	Pin 1	grey
+5V	Pin A	white
GND	Pin B	Inner Shield
Sensor Sin	Pin C	yellow
Sensor Cos	Pin D	green
Temp Sensor	Pin E	black
Housing		Outer Shield

N-Connector



View: motor connector, plug side

**MOTOR CABLES FOR GM51-23**



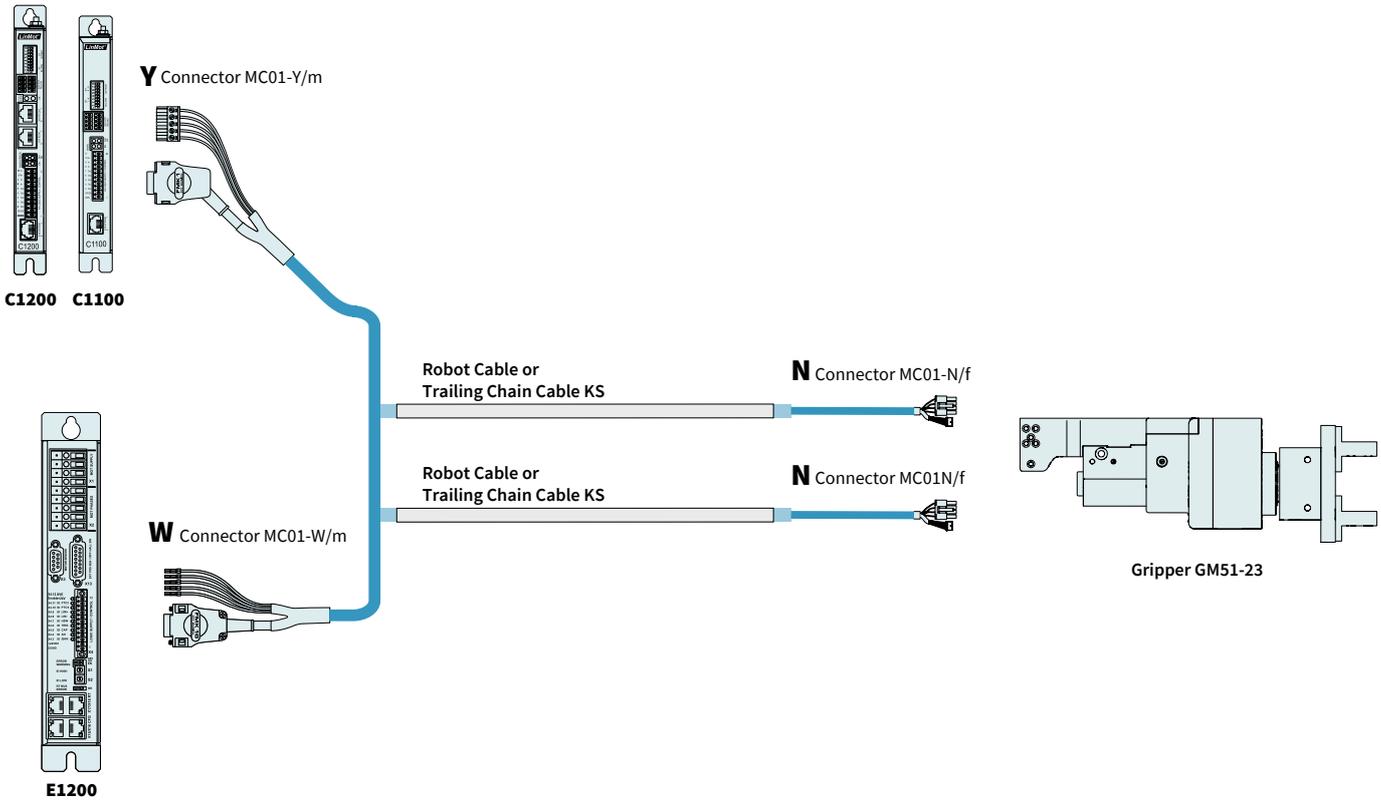
**TRAILING CHAIN CABLES**

Item	Description	Item-No.
<b>KS03-W/K-2</b>	Trailing Chain Cable W/K, 2 m	<a href="#">0150-2187</a>
<b>KS03-W/K-4</b>	Trailing Chain Cable W/K, 4 m	<a href="#">0150-2369</a>
<b>KS03-W/K-6</b>	Trailing Chain Cable W/K, 6 m	<a href="#">0150-2370</a>
<b>KS03-W/K-</b>	Special Cable W/K, Custom length	<a href="#">0150-3357</a>
<b>KS03-Y/K-2</b>	Trailing Chain Cable Y/K, 2 m	<a href="#">0150-2446</a>
<b>KS03-Y/K-4</b>	Trailing Chain Cable Y/K, 4 m	<a href="#">0150-2447</a>
<b>KS03-Y/K-6</b>	Trailing Chain Cable Y/K, 6 m	<a href="#">0150-2448</a>
<b>KS03-Y/K-</b>	Special Cable Y/K, Custom length	<a href="#">0150-3516</a>
<b>KS03-R/K-1</b>	Trailing Chain Cable R/K, 1 m	<a href="#">0150-2185</a>
<b>KS03-R/K-2</b>	Trailing Chain Cable R/K, 2 m	<a href="#">0150-2186</a>
<b>KS03-R/K-</b>	Special Cable R/K, Custom length	<a href="#">0150-3530</a>
<b>KS03-A/K-</b>	Special Cable A/K, Custom length	<a href="#">0150-3542</a>
<b>KS03-C/K-</b>	Special Cable C/K, Custom length	<a href="#">0150-3577</a>
<b>KS03-OE/K-</b>	Special Cable OE/K, Open end, Custom length	<a href="#">0150-4764</a>

**ROBOT CABLES**

Item	Description	Item-No.
<b>KR03-R/K-</b>	Special Cable R/K, Custom length	<a href="#">0150-3754</a>
<b>KR03-Y/K-</b>	Special Cable Y/K, Custom length	<a href="#">0150-3718</a>
<b>KS03-W/K-</b>	Special Cable W/K, Custom length	<a href="#">0150-3755</a>

**MOTOR CABLES FOR GM51-37**



**TRAILING CHAIN CABLES**

Item	Description	Item-No.
<b>KS05-W/N-2</b>	Trailing Chain Cable W/N, 2 m	<a href="#">0150-2296</a>
<b>KS05-W/N-4</b>	Trailing Chain Cable W/N, 4 m	<a href="#">0150-2297</a>
<b>KS05-W/N-6</b>	Trailing Chain Cable W/N, 6 m	<a href="#">0150-2298</a>
<b>KS05-W/N-8</b>	Trailing Chain Cable W/N, 8 m	<a href="#">0150-2299</a>
<b>KS05-W/N-</b>	Special Cable W/N, Custom length	<a href="#">0150-3412</a>
<b>KS05-Y/N-2</b>	Trailing Chain Cable Y/N, 2 m	<a href="#">0150-2442</a>
<b>KS05-Y/N-4</b>	Trailing Chain Cable Y/N, 4 m	<a href="#">0150-2443</a>
<b>KS05-Y/N-6</b>	Trailing Chain Cable Y/N, 6 m	<a href="#">0150-2444</a>
<b>KS05-Y/N-8</b>	Trailing Chain Cable Y/N, 8 m	<a href="#">0150-2445</a>
<b>KS05-Y/N-</b>	Special Cable Y/N, Custom length	<a href="#">0150-3509</a>
<b>KS05-A/N-</b>	Special Cable A/N, Custom length	<a href="#">0150-3551</a>
<b>KS05-C/N-</b>	Special Cable C/N, Custom length	<a href="#">0150-3517</a>
<b>KS05-R/N-</b>	Special Cable R/N, Custom length	<a href="#">0150-3486</a>
<b>KS03-OE/N-</b>	Special Cable OE/N, Open end, Custom length	<a href="#">0150-6071</a>
<b>KS05-OE/N-</b>	Special Cable OE/N, Open end, Custom length	<a href="#">0150-3716</a>

**MOTOR CABLES FOR GM51-37**

ROBOT CABLES		
Item	Description	Item-No.
<b>KR05-R/N-</b>	Special Cable R/N, Custom length	<a href="#">0150-3757</a>
<b>KR05-Y/N-</b>	Special Cable Y/N, Custom length	<a href="#">0150-3514</a>
<b>KS05-W/N-</b>	Special Cable W/N, Custom length	<a href="#">0150-3406</a>

# ALL LINEAR MOTION FROM A SINGLE SOURCE

## Europe / Asia Headquarters North / South America Headquarters

### NTI AG - LinMot & MagSpring

Bodenaeckerstrasse 2  
CH-8957 Spreitenbach  
Switzerland

☎ +41 (0)56 419 91 91

☎ +41 (0)56 419 91 92

✉ office@linmot.com

🏠 www.linmot.com

### LinMot USA, Inc.

N1922 State Road 120, Unit 1  
Lake Geneva, WI 53147  
United States

☎ 262-743-2555

✉ usasales@linmot.com

🏠 www.linmot.com