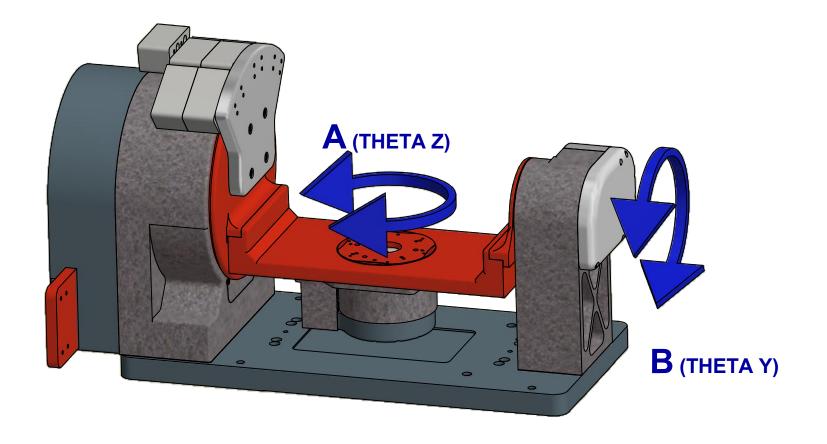


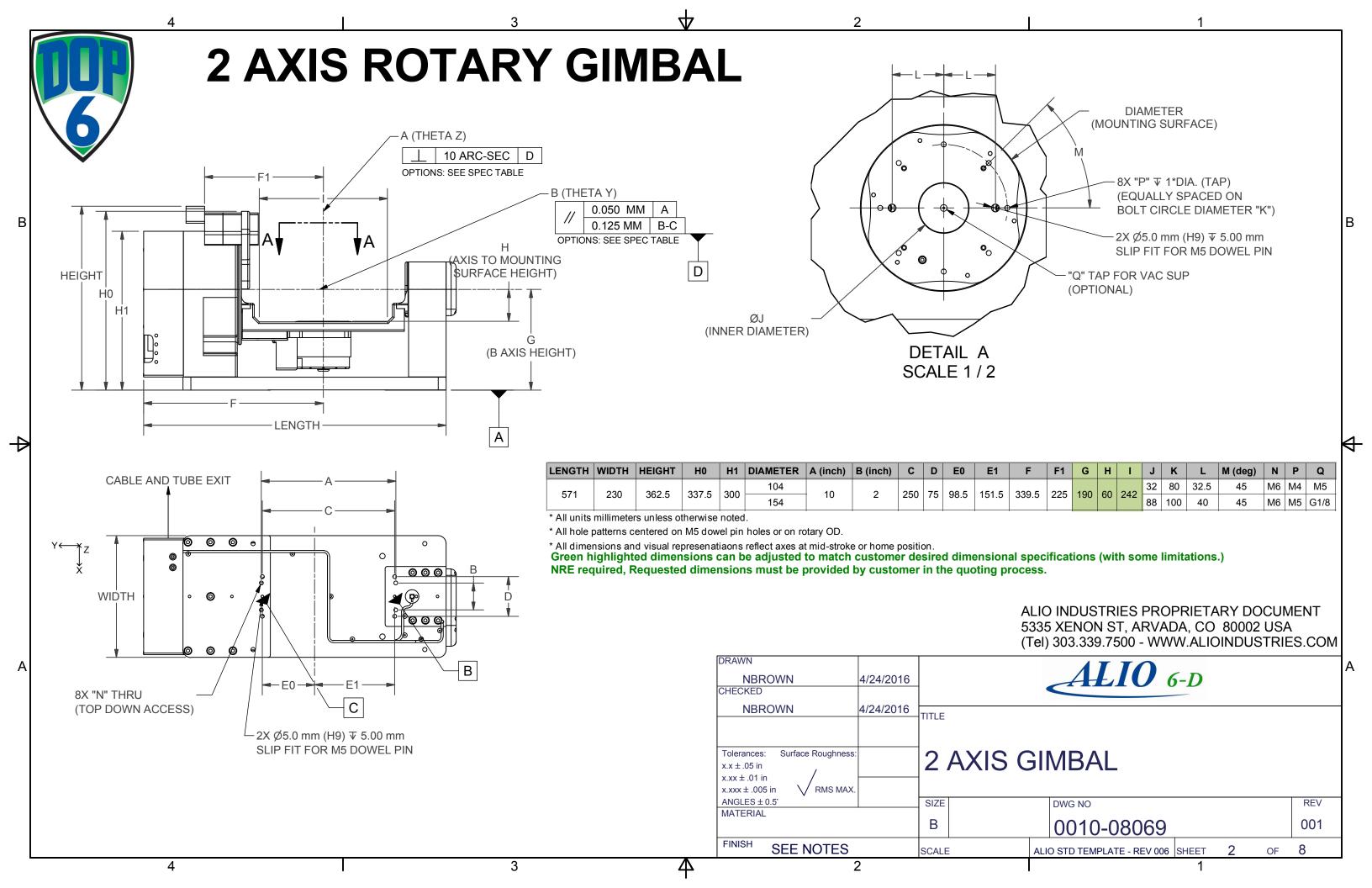
2 AXIS ROTARY GIMBAL



	STANDARD FEATURES
Stage	2 Axis Rotary Gimbal
Travel	2 Degrees of Freedom (Theta Y, Theta Z)
A Angular Travel	360 degrees continuous (Theta Z)
B Angular Travel	+/- 100 degrees (Theta Y) >> [Travel Expandable to +/- 172 deg]
Max Payload	12.0 kg (with Options for Higher Payload)
Motor	Frameless Torque Motor
	Optional: With Integrated Pneumatic Brakes
Feedback	Non-Contact Optical Encoder
Scale	Stainless Steel Ring
Angular Resolution	< 0.02 arc-sec
Sensors	Integrated Home
Bearings	Angular Contact
Hard Stops	Metal-on-Metal Hard Stop
Counterbalance	Counterweight Capability (Adjustable with Provided Weights)
Cables	High Flex, 10M Cycle, 3m Length
Vacuum Supply	Optional: Vacuum Line Plumbed to Center of Rotary Mounting
	Surface for Customer Supplied Vacuum Chuck
Pneumatic Purge	All Rotary Axes Have Air Purge Included
	Connect Supplied Hoses to CDA Air Supply
Transport	Reuseable Shippping Stop / Lift Eye Bolts Supplied
Structure	Anodized Aluminum 6061-T6
Environment	Standard
Temperature	0°C to 50°C
Humidity	10% to 80% Non-Condensing
Precision	6-D Nano Precision TM Test Methods

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DRAWN NBROWN CHECKED NBROWN M/24/2016		ALIO 6-D	
NBROWN 4/24/2016	TITLE		
Tolerances: Surface Roughness: x.x ± .05 in x.xx ± .01 in x.xxx ± .005 in RMS MAX.	2 AXIS C	SIMBAL	
ANGLES ± 0.5°	SIZE	DWG NO	REV
MATERIAL	В	0010-08069	001
FINISH SEE NOTES	SCALE	ALIO STD TEMPLATE - REV 006 SHEET 1	of 8



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NBROWN

Tolerances:

 $x.x \pm .05$ in

 $x.xx \pm .01$ in

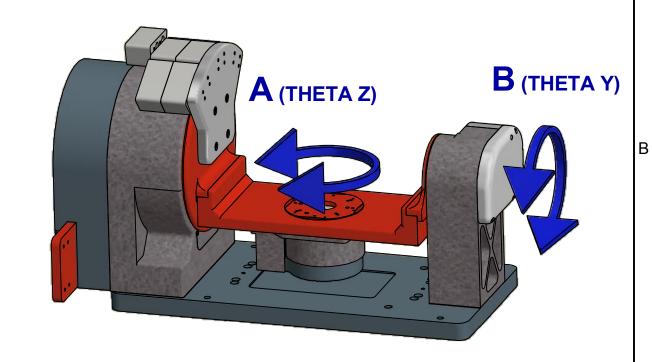
MATERIAL

 $x.xxx \pm .005$ in

ANGLES ± 0.5°

ROTARY SPECIFICATIONS

MODEL	UNITS		AI-TM-104RA	<u> </u>		AI-TM-154RA		AI-TM-208RA-GMB-CB			
AXIS		A (THETA Z)			A (THETA Z)			B (THETA Y)			
TRAVEL DEFINED FROM HOME	deg		degrees continu	HOUS	360 degrees continuous			+/- 100			
TRAVEL BETWEEN HARD STOPS (+/- 0.5 deg)	deg	300		uous				+/- 100.5			
TRAVEL BETWEEN LIMITS (+/- 0.5 deg)	deg		n/a			n/a			lo Limits Incl		
TRAVEL OPTIONS		LIMIT	LIMIT TO ANY +/- DEGREES		LIMIT	O ANY +/- DE	GREES			2 DEGREES	
ENCODER INFORMATION		LIIVIII	IOANT 17-DE	GILLO	LIIVIIII	O AINT 17- DL	GILLO	INAVEL	10 17- 17	2 DEGREES	
MODEL				Pen	ishaw Tonic w	rith RESM Stai	nless Steel Di	ng.			
TYPE				ixen		g Output Sin/C		iig			
LINES PER REVOLUTION	lines/rev		15744			23600	OS L'ICOGEI		31488		
PERFORMANCE SPECIFICATIONS [2]	IIIIes/Iev	STD	ULTRA	NANO	STD	ULTRA	NANO	STD	ULTRA	NANO	
ANGULAR ACCURACY WITHOUT COMPENSATION	arc-sec	310	n/a	INAINO	310	n/a	INANO	310	n/a	INAINO	
ANGULAR ACCURACY WITH COMPENSATION	arc-sec		n/a	+/-3		n/a	+/-3		n/a	+/-3	
BIDIRECTIONAL ANGULAR REPEATABILITY	arc-sec	'	+/- 0.5	17-3	'	+/- 0.5	17-3		+/- 0.4		
RESOLUTION (ANALOG - STANDARD)	arc-sec		0.02 arc-sec			0.01 arc-sec			0.01 arc-se		
AXIAL RUNOUT (STANDARD)	um	10	4	2	10	4	2	10	5	3	
RADIAL RUNOUT (STANDARD)	um	10	4	2	10	4	2	10	5	3	
AXIS WOBBLE	arc-sec	12	8	6	16	10	8	10	7	5	
WOBBLE AND RUNOUT OF PAYLOAD		12	0	-		r mounting and	-	-	- '		
B PARALLELISM TO MOUNTING SURFACE	um/200mm		_	Customeri		i mounting and	i aligititietit oi	100	50	15	
A PERPENDICULARITY TO MOUNTING SURFACE	um/100mm	25	10	4	25	10	4	100	- 50	15	
A - B AXIS INTERSECTION		20	10	4	25	10	4	25	10	3	
B AXIS TO A MOUNT SURFACE DISTANCE	um mm	60 mm 1/ 0.5 mm h			Nominal (exact distance provided for each						
MOTION PROFILE SPECIFICATIONS	111111		00 11111	11 +/- 0.5 1111111	voriiriai (exac	t distance prov	ided for each	3/N at Shipin	ent)		
MAX VELOCITY [3]	deg/sec	360 40		nd/200)	360 40	alaaa (- 6 20 ra	nd/200)	360 46	alooo (- 6 29) rad/222	
MAX ACCELERATION [3]	deg/sec^2	360 deg/sec (~6.28 rad/sec)			360 deg/sec (~6.28 rad/sec) 1600 deg/sec (~28 rad/sec)			360 deg/sec (~6.28 rad/sec) 2300 deg/sec (~40 rad/sec)			
ASSEMBLY MASS (WITH COUNTERWEIGHT)		1600 deg/sec (~28 rad/sec)			39			2300 deg/sec (~40 rad/sec)			
MAX LOAD (AXIAL)	kg kg		12		12		40				
MAX LOAD (RADIAL)	kg		12		12			40			
CUSTOMER SPECIFIED PAYLOAD	kg		12		8 kg (+/- 4 kg or 12kg maximum)			40			
CUSTOMER SPECIFIED FATEOAD CUSTOMER PAYLOAD CENTER OF GRAVITY	mm			40mm (Abov		unting Surface		opondont)			
MOVING MASS (NO LOAD, NO COUNTERWEIGHT)			1	40IIIII (Abov		unting Sunace	- Fayioau iilu		8.9		
MOVING MASS (12KG LOAD AND COUNTERWEIGHT)	kg kg		13		13			26.3			
ROTATING MASS MOMENT OF INERTIA (NO LOAD,	, kg		13		13			20.3			
NO COUNTERWEIGHT)	ka*mm\2		1020		1020			60000			
ROTATING MASS MOMENT OF INERTIA (12KG LOAD	kg*mm^2		1020		1020			60000			
AND COUNTERWEIGHT)	kg*mm^2		95000		95000		190000				
MOTOR INFORMATION	kg IIIII Z		93000			93000			190000		
MOTOR TYPE					EDAMEI	ESS TORQUE	MOTOR				
MOTOR MODEL			AI-TM-089-B9`	·	1	AI-TM-133-CN			AI-TM-178-E	DEV	
MAGNETIC PITCH (N-N)	deg			<u> </u>			N .		40	DC 1	
MAX VOLTAGE (LINE TO LINE) [4]	VDC	60		26 300		340					
MAX MOTOR TEMP	°C	340									
THERMAL SENSOR		155 NONE		100		155 NONE					
MOTOR CONNECTION		NONE WYE		PTC 1kO / KTY83-122 WYE		NONE WYE					
TORQUE CONSTANT	Nm/Arms		0.68								
PHASE RESISTANCE (@25° C) [5]	Ohm		3.9		2.09				2.50 3.1		
INDUCTANCE			8.9			4.2 11.5			19.1	DRAWN	
CONTINUOUS TORQUE [6]	mH Nm									DRAWN	
	Nm Armo		2.6			10.0 4.8			15.0	NBRO	
CONTINUOUS CURRENT [6]	Arms		3.8			20.6			6.0	CHECKED	
PEAK TORQUE [4]	Nm		8.2			20.0			48.0	NDDO	



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ALIO 6-D

Notes:

PEAK CURRENT [4]

BACK EMF CONSTANT

- 1. Specifications on this page are specific to customer payload and this application.
- 2. Specifications measured on stage centerline, 25mm above mounting surface. ALIO provides NIST traceable proof for all options/spec per quote.
- 3. Stage limitations are for peak customer payload and specified mass moment of inertia with payload and counterweight. Does not account for drive or resolution limitations.

12.0

- 4. Maximum on time at peak operating limits is 10 seconds. Back EMF plus IR drop must not exceed maximum line to line bus voltage
- 5. Resistance values do not include cable resistance. Cable resistance adds 0.3 ohm/m. All electrical specifications may vary by 12% from listed values.
- 6. Continuous operating limits are based on continuous operation at maximum temperature with aluminum heat sink (300mm x 300mm x 25mm).

Arms

Vrms/krpm

2 AXIS GIMBAL

B DWG NO 0010

0010-08069

ALIO STD TEMPLATE - REV 006 SHEET

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13.3

SEE NOTES

RMS MAX.

Surface Roughness:

2

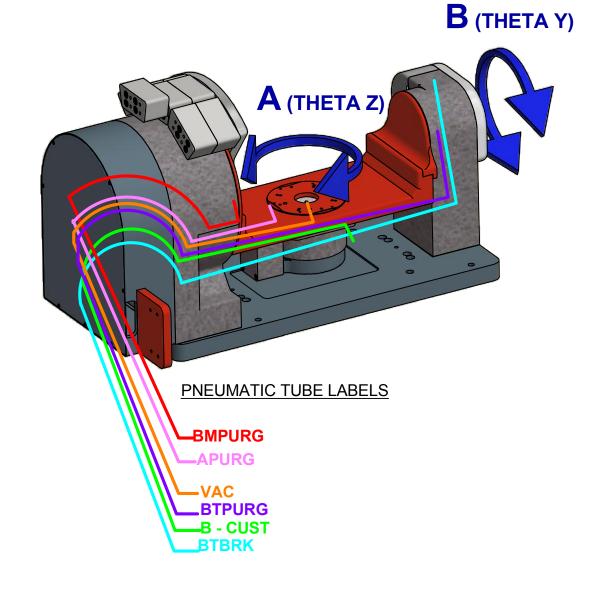
SCALE

4/24/2016

4/24/2016



AUXILIARY FEATURES



AUXILIARY FEATURES								
Pneumatic Features - Air Purge	All Rotary Axes Include Air Purge Option							
	Connect Customer Supplied Clean Dry Air Source to "APURG,"							
	"BTPURG," and "BMPURG" Labeled Tubes							
	Includes Tight Tolerance Mechanical Labyrinth Protection Internal in Rotary Stages							
Payload Air / Vacuum Supply	Optional Rotary Union for Single Pneumatic Circuit for Payload / Chuck Air or Vacuum							
(Optional)	For Customer Supplied Air / Vacuum Source to "VAC" Labeled Tube							
	M5 Tapped Port at ID of Rotary (or Use O-ring Seal of ID of Rotary)							
	Bearing Supported, Maintenance Free, Pneumatic Rotary Union							
	100 Million Cycle Life Rating							
	1/4 Inch OD High Flex Poly Tube							
Safety (Optional)	Brake Option on Theta Y axis ("BTBRK")							

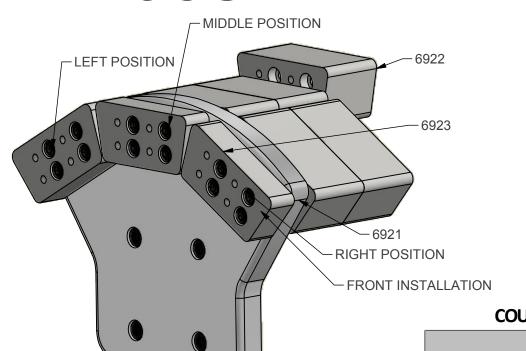
B AXIS BRAKE SPECIFICATIONS							
B AXIS BRAKE DESCRIPTION							
BRAKE LOCK (& FAILSAFE) SPRING ACTIVATED							
BRAKE RELEASE	PNEUMATIC ACTIVATED						
BRAKE SUPPLY TUBE 4mm Outer Diameter High Flex							
MINIMUM SUPPLY PRESSURE ~0.1 Mpa							
MAXIMUM SUPPLY PRESSURE 1.0 MPa							
MAXIMUM THEORETICAL	0 DEGREES						
DISPLACEMENT UPON BRAKE	0 DEGREES						
CUSTOMER TO SUPPLY AIR SUPPLY	Y AND DIGITAL OUTPUT CONTROL OF						
PNEUMATIC VALVE FOR BRAKE AC	TIVATION						
ALIO TO SUPPLY PRESSURE REGU	LATOR AND DIGITIAL VALVE						
BRAKE ON/OFF VERIFICATION IS VI.	A INLINE PRESSURE SENSOR						
CONNECTED TO ONE DIGITAL INPU	Т						

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DRAWN NBROWN 4/24/2016 CHECKED		ALIO 6-D	
NBROWN 4/24/2016	TITLE		
Tolerances: Surface Roughness: x.x ± .05 in x.xx ± .01 in x.xxx ± .005 in RMS MAX.	2 AXIS G	SIMBAL	
ANGLES ± 0.5' MATERIAL	SIZE	DWG NO	REV
WATERIAL	В	0010-08069	001
FINISH SEE NOTES	SCALE	ALIO STD TEMPLATE - REV 006 SHEET 4 OF	8

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COUNTERBALANCE SPECIFICATIONS



BACK INSTALLATION -

COUNTERBALANCING PROCEDURE:

- 1. INSTALL 6921 ONTO THE STAGE WITH 4X M6X20 SHCS.
- 2. INSTALL 6922 ONTO 6921 WITH 4X M5X35 SHCS EACH UNTIL IT IS "CLOSE"
- THE GOAL IS FOR THE STAGE NOT TO SWING BACK QUICKLY WHEN RELEASED FROM REST FROM ANY NON-HOME POSITION.
- 3. INSTALL 6923 ONTO 6921 OR 6922 WITH 4X M5X16 SHCS EACH UNTIL THERE IS NO MOVEMENT WHEN RELEASED FROM REST FROM ANY NON-HOME POSITION.

NOTE: 6922 AND 6923 MAY BE INSTALLED ON THE FRONT OF 6921 IF DESIRED. IMPORTANT: RIGHT AND LEFT POSITIONS ON 6921 CANNOT SUPPORT MORE THAN 2X 6922. IF MORE COUNTERBALANCE IS REQUIRED, INSTALL ON FRONT OR IN MIDDLE POSITION.

SEE CONFIGURATION TABLE BELOW FOR PRE-DETERMINED COUNTERBALANCE ARRANGMENTS. SHOWN: CONFIGURATION FOR 12 KG LOAD WITH LOAD CG @ 40MM ABOVE THETA Z MOUNT SURFACE.

COUNTERBALANCE CHARACTERISTICS

PHYSICAL CHARACTERISTICS								
ΜΛΤΕΡΙΛΙ	NANCC	ROUGH DIMENSIONS	MOUNTING HARDWARE					
IVIATENIAL	IVIASS	(WXHXD) (MM)	(4X EACH)					
ALUMINUM	0.8 KG	193X147X15	M6X20 SHCS					
STEEL (ELECTOLESS NICKEL PLATED)	0.5 KG	70X32X35	M5X35 SHCS					
STEEL (ELECTOLESS NICKEL PLATED)	0.2 KG	70X32X17	M5X16 SHCS					
	CONFIGURATION	NS						
NOTOVD	IOVD: 8 KC	AUTH CC @ 40 NANA	LOAD: 12 KG WITH CG @					
NO LOAD	LUAD. 6 KG	WITH CG @ 40 IVIIVI	40 MM					
2X 6922		2X 6922 2X 692						
1X 6922 + 1X 6923	3X	6922 + 1X 6923	3X 6922 + 1X 6923					
2X 6922		2X 6922	2X 6922 + 1X 6923					
	MATERIAL ALUMINUM STEEL (ELECTOLESS NICKEL PLATED) STEEL (ELECTOLESS NICKEL PLATED) NO LOAD 2X 6922 1X 6922 + 1X 6923	MATERIAL MASS ALUMINUM 0.8 KG STEEL (ELECTOLESS NICKEL PLATED) STEEL (ELECTOLESS NICKEL PLATED) CONFIGURATION NO LOAD LOAD: 8 KG N 2X 6922 1X 6922 + 1X 6923 3X	MATERIAL MASS ROUGH DIMENSIONS (WXHXD) (MM) ALUMINUM 0.8 KG 193X147X15 STEEL (ELECTOLESS NICKEL PLATED) 0.5 KG 70X32X35 STEEL (ELECTOLESS NICKEL PLATED) 0.2 KG 70X32X17 CONFIGURATIONS NO LOAD LOAD: 8 KG WITH CG @ 40 MM 2X 6922 2X 6922 1X 6922 + 1X 6923 3X 6922 + 1X 6923					

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QWOLF CHECKED	10-12-2016				ALIO 6-L)			
Tolerances: Surface Roughness: $x.x \pm .05$ in $x.xx \pm .01$ in $x.xxx \pm .005$ in RMS MAX.		2	AXIS G	116	MBAL				
ANGLES ± 0.5°		SIZE			DWG NO				REV
MATERIAL		В			0010-08069				001
FINISH SEE NOTES		SCALE		ALIC	STD TEMPLATE - REV 006 SHEE	ΞT	5	OF	8

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M5X35 SHCS

-M6X20 SHCS

M5X16 SHCS

2

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CABLE SPECIFICATIONS

BRAKE VALVE CABLE CHARACTERISTICS

VALVE SPECIF	CATIONS						
MANUFACTURER	SMC						
MFR PART NUMBER	VT307Y-H1-02N-F						
VOLTAGE	24 VDC						
WATTAGE	1.8 W						
DUTY CYCLE	CONTINUOUS						
CURRENT	75 mA						
MAX PRESSURE	0.7 Mpa						
RESPONSE TIME	25 ms						
TUBE SIZE	4MM INPUT, 4MM OUTPUT						
LEAD CONNE	CTIONS						
RED	24V SUP / SIGNAL IN						
BLACK	24V RTN						
PRESSURE REG	GULATOR						
MANUFACTURER	SMC						
MFR PART NUMBER	AR20-N02E-Z-B						
TUBE SIZE	4MM INPUT, 4MM OUTPUT						

PRESSURE LOSS SENSOR **CHARACTERISTICS**

SENSOR CHARACTERISTICS						
MANUFACTURER	SMC					
MFR PART NUMBER	ISE30A-N01-N-LA1					
OUTPUT	NPN					
INPUT TUBE SIZE	4MM					
MAX PRESSURE	1 MPa					
LEAD CONN	ECTIONS					
BROWN	24V SUP					
BLUE	24V RTN					
BLACK	SIGNAL OUT					

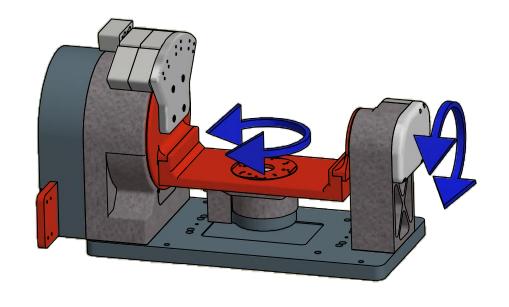
Setup settings of ISE sensor (P/N: ISE30A-N01-N-LA1) are F0 (uni = mpa);

F1 (oUt = hys)(lot = 1_p)(P_1 = 0.150)(H_1 = 0.025)(Col = 5or)

TORQUE MOTOR CABLE LEADS

LEAD CONNECTIONS							
WHITE	R PHASE						
BLACK	S PHASE						
RED	T PHASE						
SHIELD	GROUND						

^{*}Motor cables are labeled "MA" and "MB" for the A and B axes respectively.



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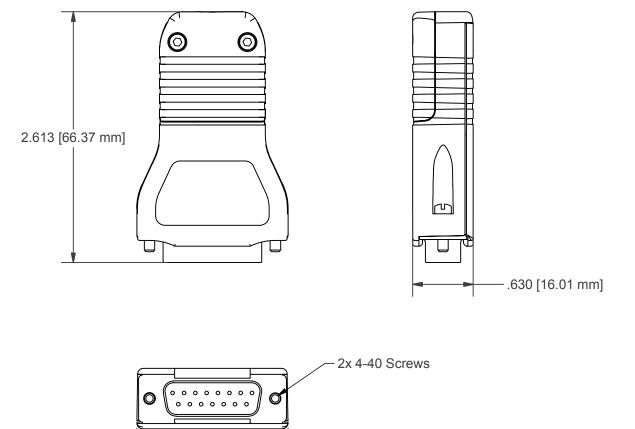
DRAWN QWOLF CHECKED	10/11/2016				ALIO 6	6-D			
Tolerances: Surface Roughness: $x.x \pm .05$ in $x.xx \pm .01$ in $x.xxx \pm .005$ in RMS MAX.		2	AXIS G	116	MBAL				
ANGLES ± 0.5* MATERIAL		SIZE			DWG NO				REV
IVII VI LI XII XL		В			0010-08069				001
FINISH SEE NOTES		SCALE		ALIC	STD TEMPLATE - REV 006	SHEET	6	OF	8

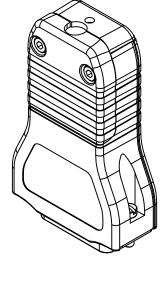
INTERFACE SPECIFICATIONS

ENCODER INTERFACE PINOUT

FUNCTION	SIGNAL	ANALOG ENCODER P/N: AI-TI-0000 ONLY
CABLE CONNECTOR	TYPE	D-SUB 15 PIN MALE
CUSTOMER MATING CONNECTOR	TYPE	D-SUB 15 PIN FEMALE
POWER	5V	4,5
	0V	12,13
SINE & COSINE INCREMENTAL SIGNALS	V1+	9
	V1-	1
	V2+	10
	V2-	2
REFERENCE MARK	R+	3
	R-	11
LIMITS	Р	7
	Q	8
SHIELD	Inner Shield	nc
	Outer Shield	Case

- 1. Multiple 5V and 0V pins are redundant and only one pin is required to be connected.
- 2. Encoder cables are labeled "EA" and "EB" for the A and B axes respectively.





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DRAWN QWOLF CHECKED	2016-17-10	ALIO 6-D							
Tolerances: Surface Roughness: $x.x \pm .05$ in $x.xx \pm .01$ in $x.xxx \pm .005$ in RMS MAX.		TONIC INTERFACE							
ANGLES ± 0.5° MATERIAL		SIZE			DWG NO			REV	
Generic		В			TONIC INTERF				
FINISH SEE NOTES		SCALE		ALIC	STD TEMPLATE - REV 006 SHEET	7	OF	8	

