

CHARACTERISTICS

The **MTJZ** series contains Z-axis Linear Units with toothed belt drive, integrated Ball rail system and compact dimensions. This Linear Units provide high performance features such as, high speed, good accuracy and repeatability by vertical applications.

They can easily be combined to multi-axis systems.

Excellent price-/performance ratio and quick delivery time are ensured.

The compact, precision-extruded aluminum Profile from 6063 AL with integrated Zero-backlash Ball rail guide system, allows high load capacities and optimal cycles for the movement of larger masses at high speed.

In the linear units MTJZ is used a pre-tensioned steel reinforced AT polyurethane timing toothed belt. In conjunction with a Zero-backlash drive pulley high moments with alternating loads with good positioning accuracy, low wear and low noise can be realized.

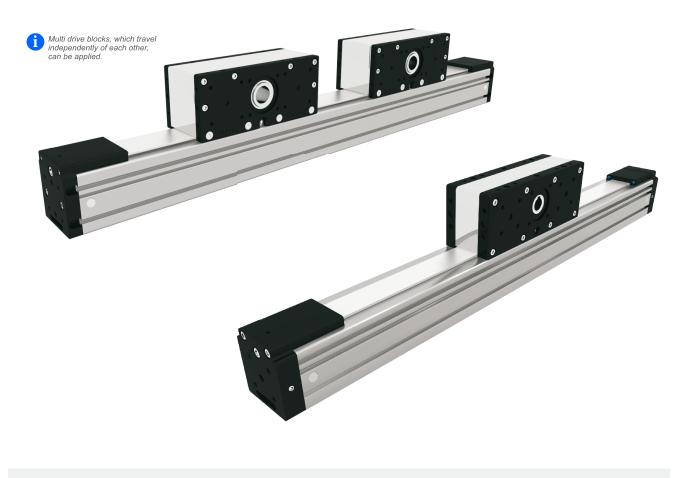
The in the Profile slot driving Polyurethane timing belt protects all the parts in the Profile from dust and other contaminations

The aluminum Profile includes T-slots for attaching sensors and switches. Also, a Reed switch can be used here.

The drive block provides the possibility to attach a Motor or Gearbox housing and additional accessories on it.

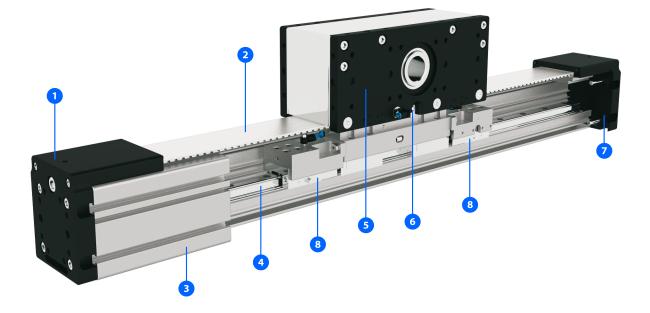
Central lubrication port on the drive block allows easy re-lubrication of the Ball rail guide.

For the linear units MTJZ various adaptation options, for attaching (or redirecting), for Motors or Gearboxes are available.



The aluminium profiles are manufactured according to the medium EN 12020-2 standard Straightness = 0,35 mm/m; Max. torsion = 0,35 mm/m; Angular torsion = 0,2 mm/40 mm; Parallelism = 0,2 mm

STRUCTURAL DESIGN



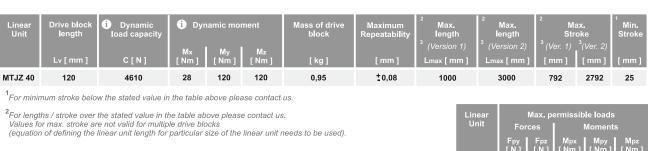
- 1 Tension End with integrated belt tensioning system
- 2 AT polyurethane toothed belt with steel tension cords
- **3** Aluminium profile-Hard anodized
- 4 Linear Ball Guideway
- 5 Drive block with pulley, Motor flange; with built in Magnets6 Central lubrication port; both sides
- 7 Tension End with integrated belt tensioning system
- 8 Clamping and braking element for linear guideway

HOW TO ORDER

	MTJZ -	65	- 700	- 10	- 0	- 2	- 35
Series :							
MTJZ							
Size :							
0							
55							
30							
10							
Absolute Stroke [mm] : (Absolute stroke = Effective stroke + 2 x	Safety stroke)]				
ype of drive pulley :							
: Pulley with through hole							
I: Pulley with journal							
0 : Pulley with journal (without Keyway)	1						
2: Pulley with journal on both sides							
20 : Pulley with journal on both sides (wi		h. h l -					
MTJZ 110 only available with drive p	ulley with througi	n noie					
Clamping element :							
: Without							
: With (available only for MTJZ 110)							
Only as emergency break!							
lumber of drive blocks :							

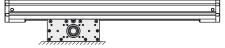
Leave blank : For the case of one drive block

General technical data

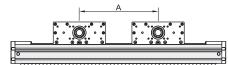


³Mounting versions

Version 1: Mounting by the drive block, profile travels



Version 2: Mounting by the profile, drive blocks travel

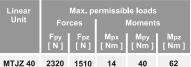


Multiple drive blocks, which travel independently of each other, can be applied.

7 Recommended values of loads

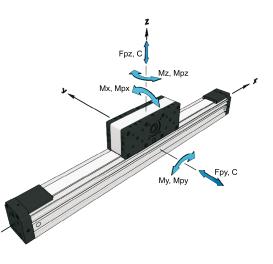
All the data of dynamic moments and load capacities stated in the upper table are theoretical without considering any safety factor. The safety factor depends on the application and its requested safety. We recommend a minimum safety factor (fs =5.0)

Modulus of elasticity: $E = 70000 \text{ N} / mm^2$





For operating temperature out of the presented range, please contact us.



Drive and belt data

Linear Unit	* Max. travel speed	Max. drive torque	No load torque of drive block	Puley drive ratio	Pulley diameter	Belt type	Belt width	Max. force transmited by belt	Specific spring constant	* Max. acceleration
	[m/s]	[Nm]	[Nm]	[mm / rev]	[mm]		[mm]	[N]	C _{spec} [N]	[m/s ²]
MTJZ 40	5	3,6	0,2	99	31,51	AT3	20	230	225000	70

 * For travel speed and acceleration over the stated value in the table above please contact us.

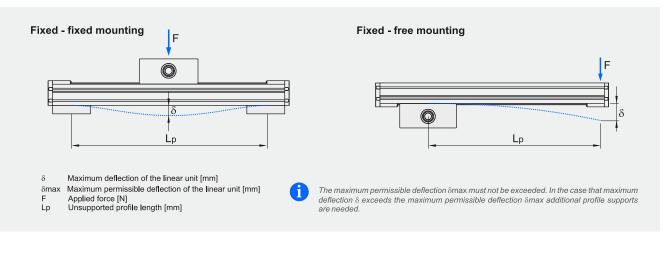
Linear Unit	* Mass of I	* Mass of linear unit		
	[k	g]	ly [cm ⁴]	lz [cm ⁴]
MTJZ 40	1,7 + 0,0023 × (Abs. stroke -	+ (nb - 1) × A) + 0,95 × (nb - 1)	9,8	11,6
*Absolute stroke [mm] A - Distance between nb - Number of drive b	two drive blocks [mm]	Mass calculation doe	sn´t include ma	ass of motor, rea

Mass moment of inertia

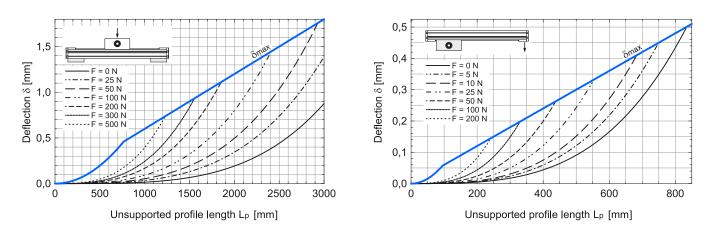
Linear Unit	* Mass moment of inertia (Version 1) [10 ⁻⁴ kg m ²]	Mass moment of inertia of drive block (Version 2) [10 ⁻⁴ kg m ²]
MTJZ 40	2,1 + 0,0058 × (Abs. stroke + (nb - 1) × A) + 0,22 × (nb - 1)	2,6
*Absolute stroke [mm]		

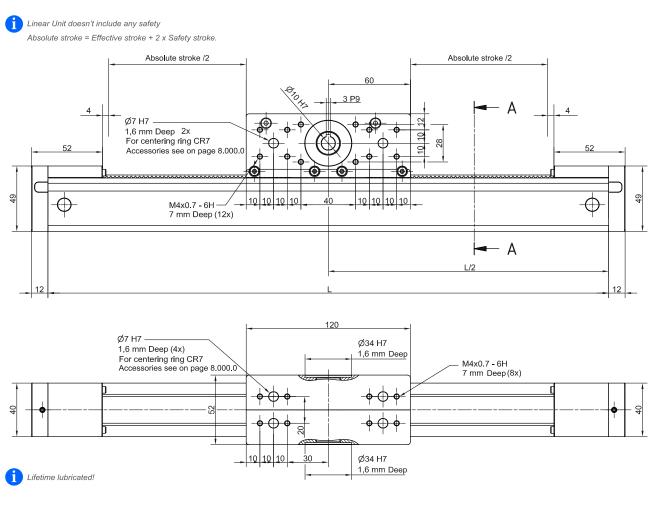
A - Distance between two drive blocks [mm] nb - Number of drive blocks

Deflection of the linear unit



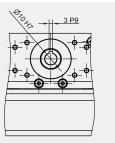
MTJZ 40

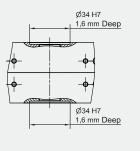




All dimensions in mm; Drawings scales are not equal.

TYPE 0





TYPE 1

i Journal with or without Keyway.

Ø34 H7

20

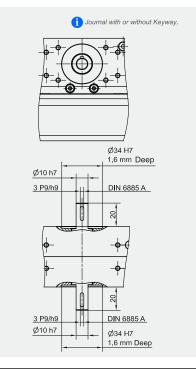
DIN 6885 A

Ø34 H7 1,6 mm Deep

-#

1,6 mm Deep

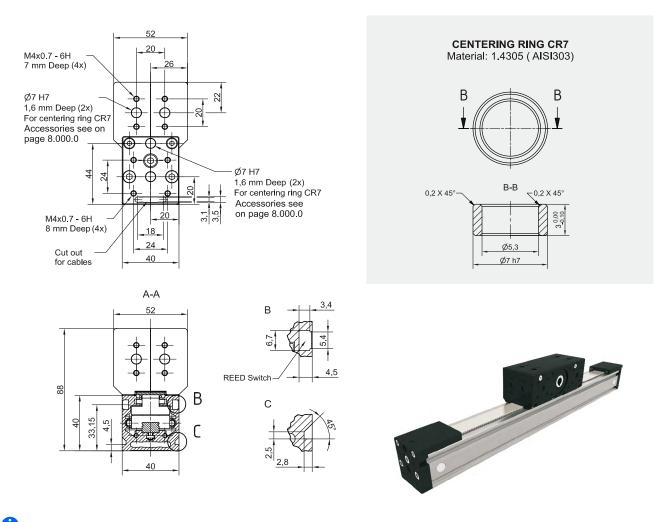
TYPE 2



4,5

<u>3 P9/h9</u>

Ø10 h7



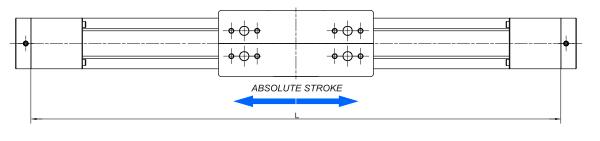
1

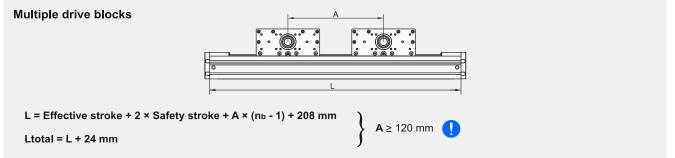
All dimensions in mm; Drawings scales are not equal.

Defining of the linear unit length

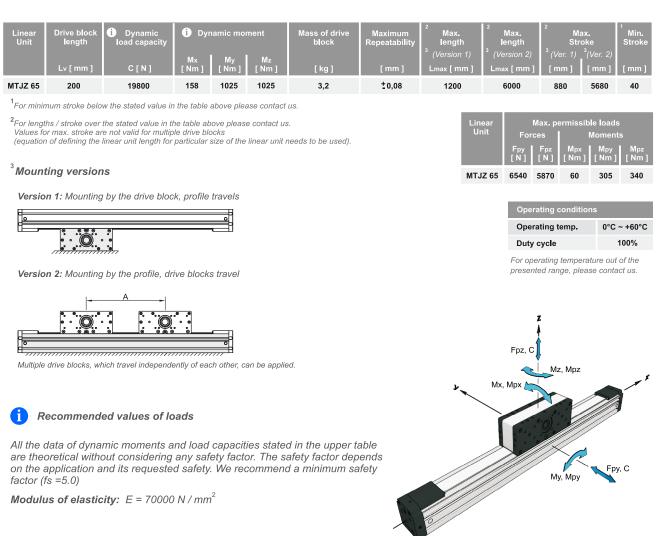
L = Effective stroke + 2 × Safety stroke + 208 mm

Ltotal = L + 24 mm





General technical data



Drive and belt data

Linear Unit	* Max. travel speed	Max. drive torque	No load torque of drive block	Puley drive ratio	Pulley diameter	Belt type	Belt width	Max. force transmited by belt	Specific spring constant	* Max. acceleration
	[m/s]	[Nm]	[Nm]	[mm / rev]	[mm]		[mm]	[N]	C _{spec} [N]	[m/s ²]
MTJZ 65	5	13,1	0,9	165	52,52	AT5	32	500	600000	70

m *For travel speed and acceleration over the stated value in the table above please contact us.

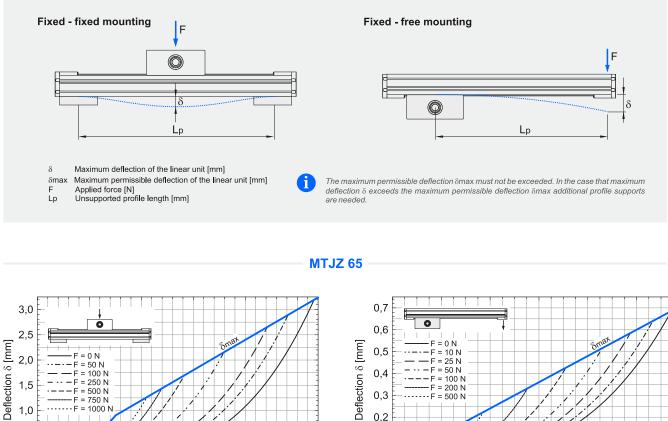
Linear Unit	*	f Mass of linear unit			
		[kg]		ly [cm ⁴]	lz [cm ⁴]
MTJZ 65	5,7 + 0,0054 × (A	Abs. stroke + (nb - 1) × A) + 3,2 × (nb - 1)	59,7	74,4
*Absolute stroke [mm] A - Distance between nb - Number of drive b		1	Mass calculation does	sn´t include ma	ss of motor, rec

Mass moment of inertia

Linear Unit	* Mass moment of inertia (Version 1) [10 ⁻⁴ kg m ²]	Mass moment of inertia of drive block (<i>Version 2)</i> [10 ⁻⁴ kg m ²]
MTJZ 65	18,9 + 0,0374 × (Abs. stroke + (nb - 1) × A) + 1,7 × (nb - 1)	23,8
*Absolute stroke [mm]		

A - Distance between two drive blocks [mm] nb - Number of drive blocks

Deflection of the linear unit

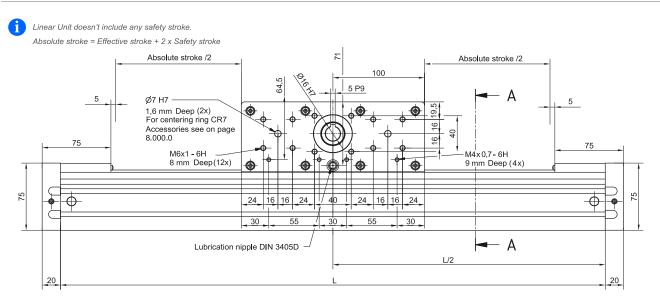


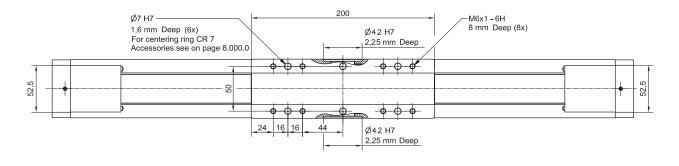
 $\begin{array}{c} \hline & F = 0 \ N \\ \hline & ---F = 10 \ N \\ \hline & ---F = 25 \ N \\ \hline & ---F = 50 \ N \\ \hline & ---F = 100 \ N \\ \hline & ---F = 200 \ N \\ \hline & ----F = 500 \ N \end{array}$ Deflection § [mm] = 0 N = 50 N = 100 N = 250 N = 500 N = 750 N = 1000 N 0,5 2,0 0,4 1,5 0,3 1,0 0,2 0,5 0,1 0,0 0,0 0 1000 2000 3000 4000 5000 0 200 400 Unsupported profile length Lp [mm] Unsupported profile length Lp [mm]

600

800

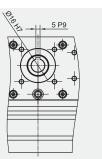
1000

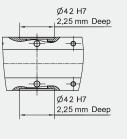




All dimensions in mm; Drawings scales are not equal.

TYPE 0





TYPE 1

i Journal with or without Keyway.

Ø42 H7

•

•-¢

DIN 6885 A

Ø42 H7 2,25 mm Deep

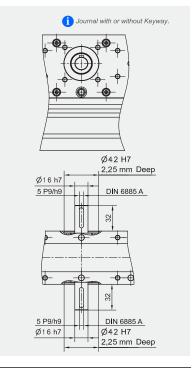
33

ø

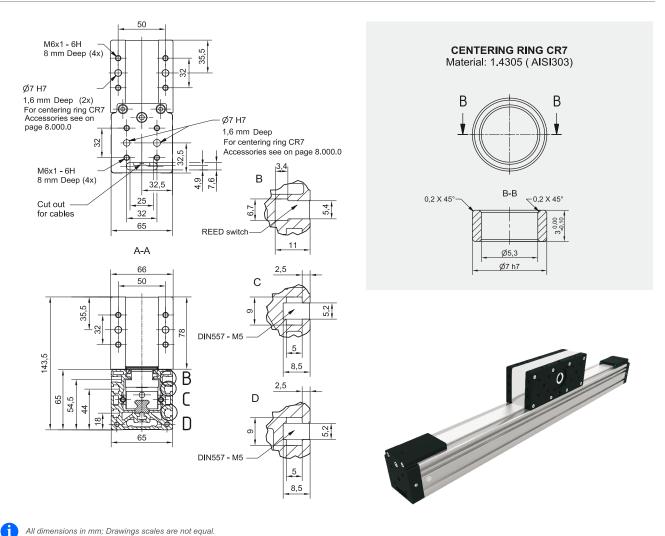
2

<u>5 P9/h9</u> Ø16 h7 2,25 mm Deep

TYPE 2



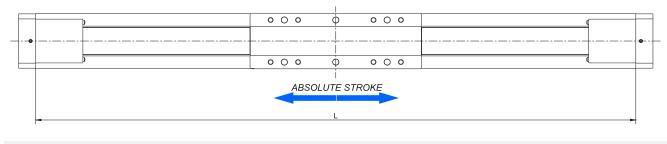
In order to improve the products in this catalogue the specifications are subject to change without notice.

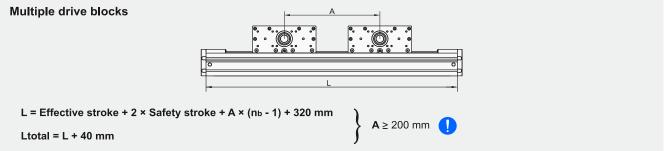


Defining of the linear unit length

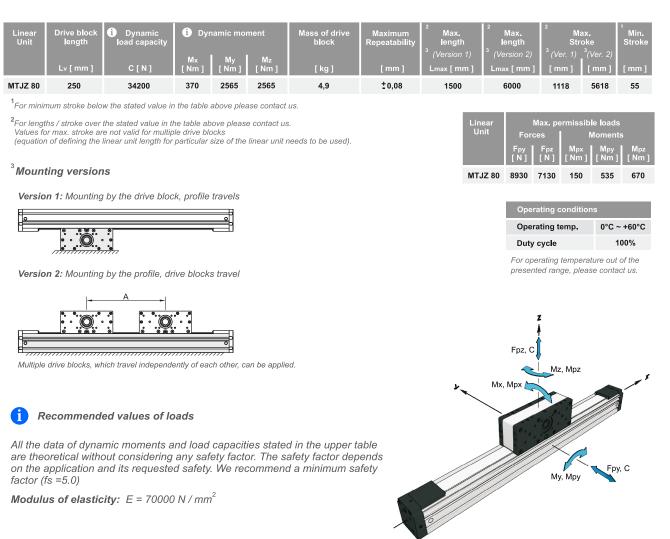
L = Effective stroke + 2 × Safety stroke + 320 mm

Ltotal = L + 40 mm





General technical data



Drive and belt data

Linear Unit	* Max. travel speed	Max. drive torque	No load torque of drive block	Puley drive ratio	Pulley diameter	Belt type	Belt width	Max. force transmited by belt	Specific spring constant	* Max. acceleration
	[m/s]	[Nm]	[Nm]	[mm / rev]	[mm]		[mm]	[N]	C _{spec} [N]	[m/s ²]
MTJZ 80	5	29,4	1,4	210	66,84	AT5	50	880	960000	70

 * For travel speed and acceleration over the stated value in the table above please contact us.

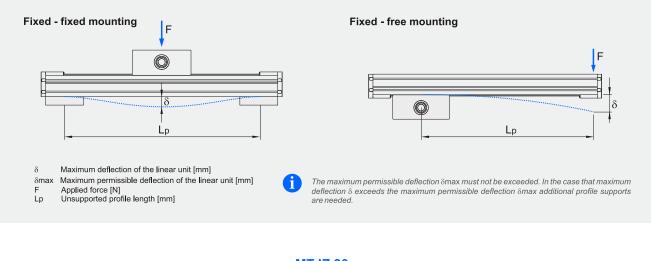
Linear Unit	* Mass of	linear unit 19]	in	noment of ertia Iz [cm ⁴]
MTJZ 80	9,7 + 0,0083 × (Abs. stroke	+ (nb - 1) × A) + 4,9 × (nb - 1)	129,1	173,4
*Absolute stroke [mm] A - Distance between nb - Number of drive b		1 Mass calculation doe	esn´t include ma	ass of motor, rec

Mass moment of inertia

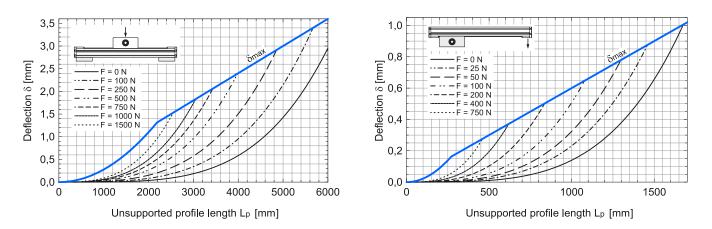
Linear Unit	Mass moment of inertia (Version 1) [10 ⁻⁴ kg m ²]	Mass moment of inertia of drive block (<i>Version 2)</i> [10 ⁻⁴ kg m ²]
MTJZ 80	60,0 + 0,0922 × (Abs. stroke + (nь - 1) × A) + 6,4 × (nь - 1)	61,1

A - Distance between two drive blocks [mm] nb - Number of drive blocks

Deflection of the linear unit

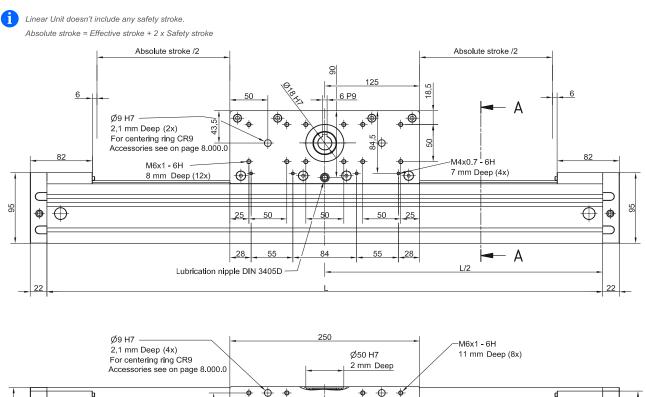


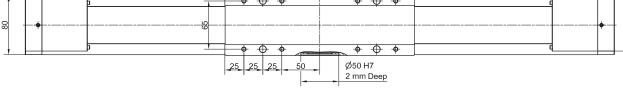
MTJZ 80



2

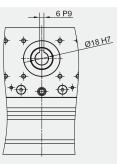
DIMENSIONS

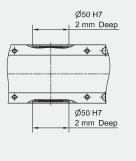




1 All dimensions in mm; Drawings scales are not equal.

TYPE 0





TYPE 1

۲

Ø50 H7

-

φ

DIN 6885 A

2 mm Deep

Ø50 H7

39

. 2 mm Deep

i Journal with or without Keyway.

-0

-\$

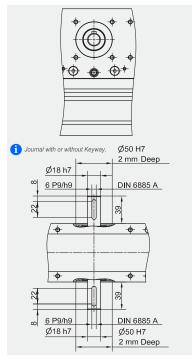
<u>6 P9/h9</u>

Ø18 h7

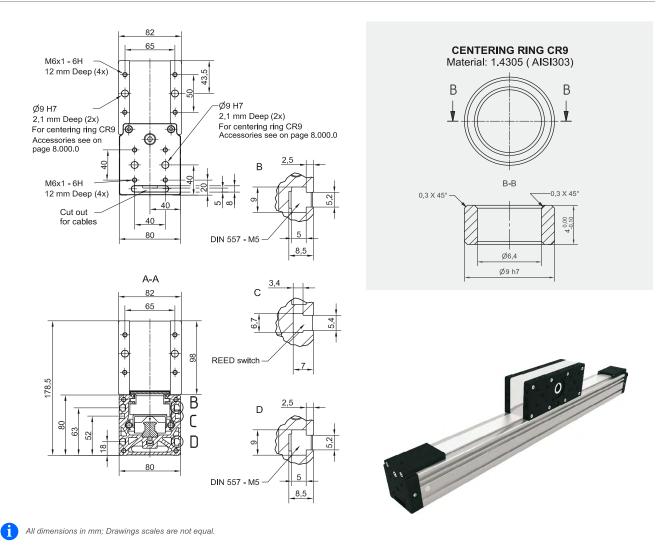
22

8

TYPE 2



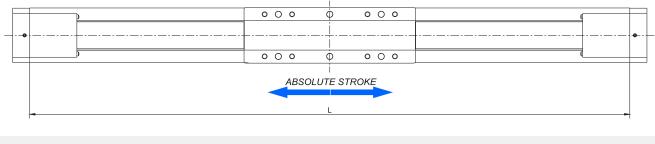
In order to improve the products in this catalogue the specifications are subject to change without notice.

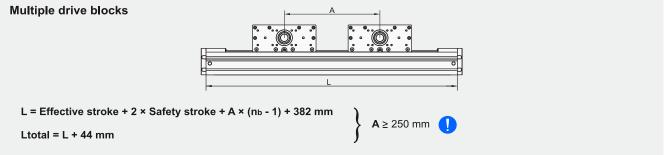


Defining of the linear unit length

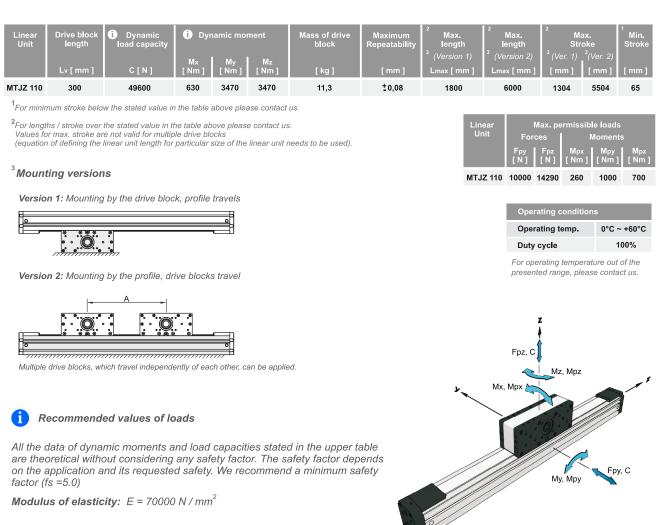
L = Effective stroke + 2 × Safety stroke + 382 mm

Ltotal = L + 44 mm





General technical data



Drive and belt data

Linear Unit	* Max. travel speed	Max. drive torque	No load torque of drive block	Puley drive ratio	Pulley diameter	Belt type	Belt width	Max. force transmited by belt	Specific spring constant	* Max. acceleration
	[m/s]	[Nm]	[Nm]	[mm / rev]	[mm]		[mm]	[N]	C _{spec} [N]	[m/s ²]
MTJZ 110	5	110,0	2,6	300	95,49	AT10	70	2300	2450000	70

 $m ^*$ For travel speed and acceleration over the stated value in the table above please contact us.

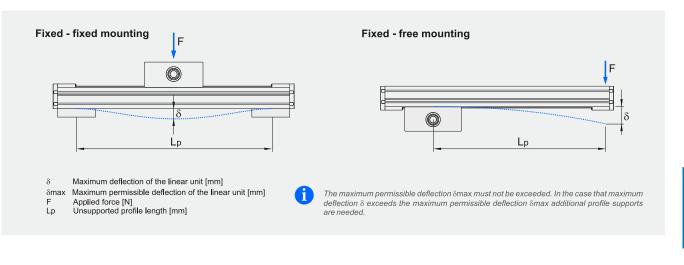
Linear Unit	* Mass	Planar moment of inertia			
		[kg]		ly [cm ⁴]	lz [cm ⁴]
MTJZ 110	21,7 + 0,0147 × (Abs. str	roke + (nь - 1) × A) + 11,3 × (nь	- 1)	513,0	620,0
*Absolute stroke [mm] A - Distance between nb - Number of drive b		Mass calcula	ation doe	sn´t include ma	ss of motor, rea

Mass moment of inertia

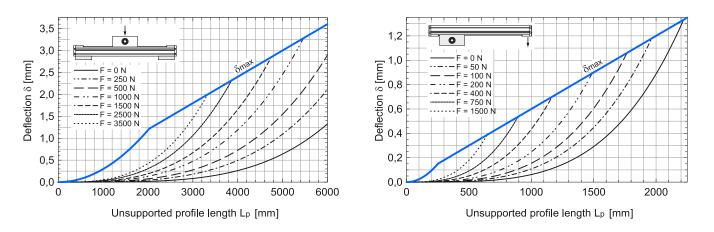
Linear Unit	 Mass moment of inertia (Version 1) [10⁻⁴ kg m²] 	Mass moment of inertia of drive block (Version 2) [10 ⁻⁴ kg m ²]
MTJZ 110	282,4 + 0,3358 × (Abs. stroke + (nb - 1) × A) + 45,3 × (nb - 1)	302,9

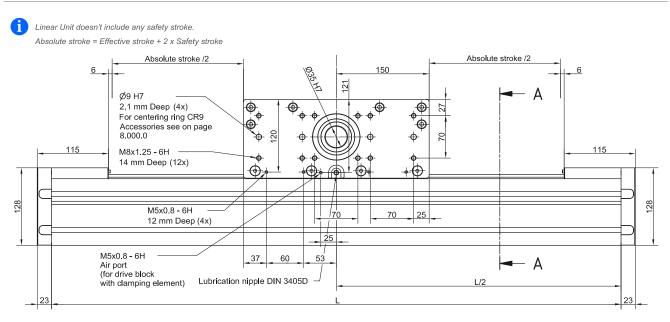
A - Distance between two drive blocks [mm] nb - Number of drive blocks

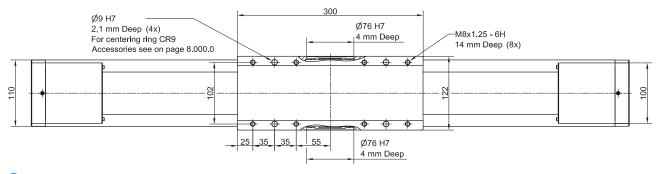
Deflection of the linear unit



MTJZ 110

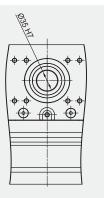


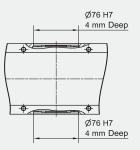




i All dimensions in mm; Drawings scales are not equal.

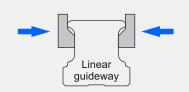
TYPE 0





Drive block with clamping element

Clamping by spring-loaded energy

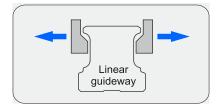


Air pressure = 0 bar

Holding force = 1400 N

Holding force is tested on clamping element using a slightly lubricated rail (ISO VG 68).

Opened by air pressure



Opening air pressure = 5,5 - 8 bar

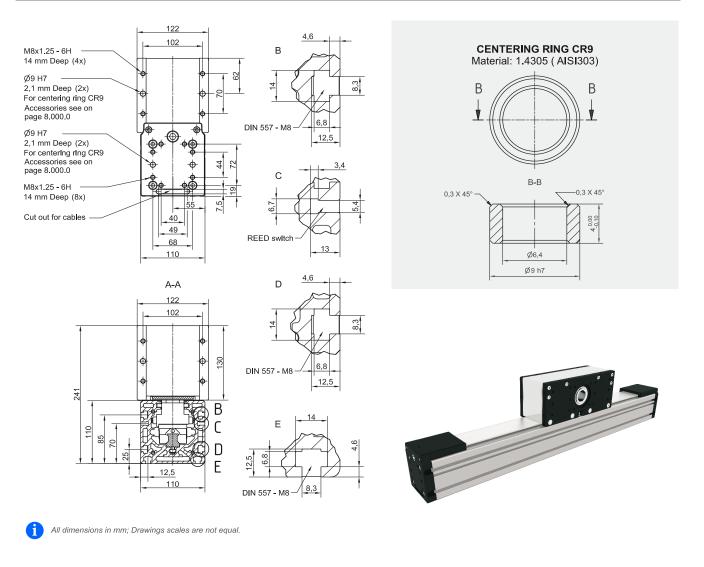
1 The air pressure opens clamping pistons. Free movement is allowed.

Purified and oiled air shall be used (according to ISO 8573-1 Class 4). Recommended filter size is $25 \ \mu m$.

Linear Unit	Mass of drive block	* Mass of linear unit
	[kg]	[kg]
MTJZ 110	12,9	23,3 + 0,0147 × (Abs. stroke + (nb - 1) × A) + 12,9 × (nb - 1)
*		

*Absolute stroke [mm] A - Distance between two drive blocks [mm]

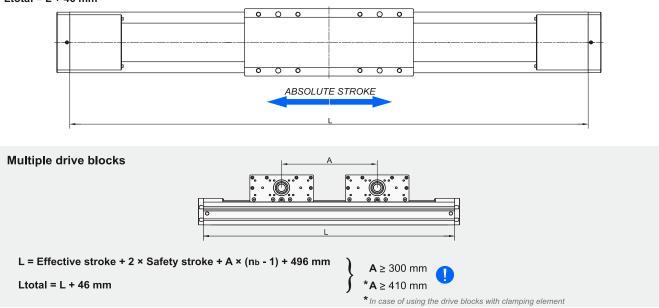
nb - Number of drive blocks



Defining of the linear unit length

L = Effective stroke + 2 × Safety stroke + 496 mm

Ltotal = L + 46 mm



In order to improve the products in this catalogue the specifications are subject to change without notice.