## Please read these Operational Instructions carefully and follow them accordingly!

Ignoring these Instructions may lead to malfunctions or to coupling failure, resulting in damage to other parts.

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## Safety and Guideline Signs



Danger of injury to personnel and damage to machines.

Please Observe!
Guidelines on important points.

## Safety Regulations

These Installation and Operational Instructions $(I+O)$ are part of the coupling delivery.
Please keep them handy and near to the coupling at all times.
It is forbidden to start initial operation of the product until you have ensured that all applicable EU directives and directives for the machine or system, into which the product has been installed, have been fulfilled.
At the time these Installation and Operational Instructions go to print, the ROBA ${ }^{\oplus}$-DS couplings accord with the known technical specifications and are operationally safe at the time of delivery.
Without a conformity evaluation, this product is not suitable for use in areas where there is a high danger of explosion. This statement is based on the ATEX directive.


ㅁ If the $\mathrm{ROBA}^{\circledR}-\mathrm{DS}$ couplings are modified.
$\square$ The relevant standards for safety and / or installation conditions are ignored.

## User-implemented Protective Measures

$\square$ Cover all moving parts to protect against seizure, dust or foreign body impact.
To prevent injury or damage, only specialist personnel are allowed to work on the components. They must be familiar with the dimensioning, transport, installation, initial operation, maintenance and disposal according to the relevant standards and regulations.
Please read the Installation and Operational Instructions carefully prior to installation and initial operation of the device.

These Safety Regulations are user hints only and may not be complete!


Fig. 1

## Installation and Operational Instructions for ROBA ${ }^{\circledR}$-DS couplings Type $95{ }_{1}^{0}$. Sizes 3 to 15

## Parts List

Only use mayr original parts

| Item | Name |
| :--- | :--- |
| $\mathbf{1 . 1}$ | Clamping hub Type 95_.4_-_ |
| $\mathbf{1 . 1 . 1}$ | Cap screw for clamping hub Type 95_.4__- |
| $\mathbf{1 . 1 . 2}$ | Washer |
| $\mathbf{1 . 2}$ | Shrink disk hub Type 95_.3_-_ |
| $\mathbf{1 . 2 . 1}$ | Hexagon head screws for shrink disk hub Type 95_.3_-_ |
| $\mathbf{1 . 2 . 2}$ | Shrink disk |
| $\mathbf{1 . 3}$ | Hub with tapered bore Type 95_.5_-_ |
| $\mathbf{1 . 4}$ | Split clamping hub Type 95_.8_-_ |
| $\mathbf{1 . 4 . 1}$ | Cap screw for split clamping hub Type 95_.8_-_ |
| $\mathbf{1 . 4 . 2}$ | Washer |
| $\mathbf{2}$ | Disk pack |
| $\mathbf{3}$ | Sleeve |
| $\mathbf{4}$ | Connection plate |
| $\mathbf{4 . 1}$ | Connection plate HSK |
| $\mathbf{5}$ | Cap screw |
| $\mathbf{6}$ | Cap screw |
| $\mathbf{7}$ | Washer |

# Installation and Operational Instructions for ROBA ${ }^{\circledR}$-DS couplings Type $95{ }_{1}^{0}$. <br> Sizes 3 to 15 

Table 1: Technical Data


Table 2:
Transmittable Torques on Clamping Hubs (1.1) - Dependent on Bore - Suitable for H7/k6

| Bore | Sizes |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
|  | 3 | 6 | 10 | 15 |
| $\varnothing 10$ | 27 | - | - | - |
| 012 | 32 | - | - | - |
| 014 | 37 | 46 | - | - |
| 015 | 39 | 51 | - | - |
| 016 | 42 | 56 | - | - |
| 018 | 47 | 65 | - | - |
| 019 | 49 | 70 | 99 | - |
| Ø20 | 52 | 74 | 105 | - |
| Ø22 | - | 84 | 116 | - |
| Ø24 | - | 92 | 128 | - |
| $\varnothing 25$ | - | 95 | 135 | 143 |
| $\varnothing 28$ | - | 107 | 151 | 163 |
| Ø30 | - | - | 162 | 177 |
| Ø32 | - | - | 173 | 191 |
| Ø35 | Attention! Please observe permitted peak torques for selected coupling size and Type. |  | 189 | 211 |
| Ø38 |  |  | - | 229 |
| 040 | - | - | - | 241 |
| $\varnothing 42$ | - | - | - | 253 |

- The transmittable torques refer to a temperature range of $-20^{\circ} \mathrm{C}$ to $+40^{\circ} \mathrm{C}$.

At temperatures over $+40^{\circ} \mathrm{C}$, the torque transmitted via frictional locking reduces by $10 \%$ per $10^{\circ} \mathrm{C}$. The max. permitted operating temperature is $+100^{\circ} \mathrm{C}$.

## Installation and Operational Instructions for ROBA ${ }^{\circledR}$-DS couplings Type $95{ }_{1}^{0}$. <br> Sizes 3 to 15

Table 3:
Transmittable Torques on Split Clamping Hubs (1.4) - Dependent on Bore - Suitable for H7/g6

| Bore | Sizes |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
|  | 3 | 6 | 10 | 15 |
| $\varnothing 10$ | 31 | - | - | - |
| 012 | 38 | - | - | - |
| 014 | 44 | 44 | - | - |
| $\varnothing 15$ | 47 | 47 | - | - |
| 016 | 50 | 50 | - | - |
| 018 | 57 | 57 | - | - |
| $\varnothing 19$ | 60 | 60 | 115 | - |
| Ø20 | 63 | 63 | 121 | - |
| $\varnothing 22$ | - | 69 | 133 | - |
| Ø24 | - | 75 | 145 | - |
| $\varnothing 25$ | - | 79 | 151 | 151 |
| $\varnothing 28$ | - | 99 | 169 | 169 |
| Ø 30 | - | - | 181 | 181 |
| Ø32 | - | - | 193 | 193 |
| Ø35 | Attention! Please observe permitted peak torques for selected coupling size and Type. |  | 211 | 211 |
| Ø38 |  |  | - | 230 |
| $\varnothing 40$ | - | - | - | 242 |
| Ø42 | - | - | - | 254 |

(i)
The transmittable torques refer to a temperature range of $-20^{\circ} \mathrm{C}$ to $+40^{\circ} \mathrm{C}$.
At temperatures over $+40^{\circ} \mathrm{C}$, the torque transmitted via frictional locking reduces by $10 \%$ per $10^{\circ} \mathrm{C}$.
The max. permitted operating temperature is $+100^{\circ} \mathrm{C}$.

Transmittable Torques on Shrink Disk Hubs
The transmittable torques on shrink disk hubs Type 95_2__ equal the maximum coupling torques.
Exception:
On Size 3 and a preferred bore $\varnothing 10$, the max.
transmittable torque is: 41 Nm .

# Installation and Operational Instructions for ROBA ${ }^{\circledR}$-DS couplings Type $95{ }_{1}^{0}$. Sizes 3 to 15 

(B.9.7.1.EN)

## Function - Application

ROBA $^{\circledR}$-DS couplings are shaft connections for torsionally rigid, backlash-free torque transmission. At the same time they compensate for angular misalignments and axial displacements on single-jointed couplings (Type 950 $\qquad$ , and additionally for radial misalignments on double-jointed couplings (Type 951. $\qquad$

## State of Delivery

ROBA ${ }^{\circledR}$-DS couplings are delivered completely manufacturerassembled.
In special cases, the $\mathrm{ROBA}^{\circledR}$-DS couplings are delivered in individual parts and pre-assembled units.

(i)
All screw connections must be checked or pretensioned during the final installation to a torque value according to Table 1.

Hubs and sleeves are made of aluminium, the disks are made of stainless steel.
The shrink disks (1.2.2) as steel components are phosphated and therefore have a basic corrosion protection. The rest of the connection elements are oiled

## Temperature Resistance

Temperature resistance of ROBA $^{\circledR}$-DS Sizes 3 to 15 from $-20^{\circ} \mathrm{C}$ up to $+100^{\circ} \mathrm{C}$.
The clamping ring hub torques transmitted via frictional locking, however, depend on bores and temperatures. (Please observe the guidelines below Table 2).

## Storage

To avoid corrosion, the coupling must be stored in dry rooms protected from the weather.
Preservative oil can be used for protecting (treating) the coupling.

## Guidelines on Hub Bore and Shaft

## General Guidelines

- The maximum bore diameter according to Table 1 may not be exceeded.
- For application with clamping hubs (1.1), a tolerance connection of H7/k6 should be selected. For application with split clamping hubs (1.4), a tolerance connection of $\mathrm{H} 7 / \mathrm{g} 6$ should be selected.
The shrink disk hubs (1.2) should have a tolerance connection of H7/g6 on bores smaller than $\varnothing 25 \mathrm{H} 7 / \mathrm{h} 6$.
- On clamping hubs (1.1) and split clamping hubs (1.4) the transmittable torques are dependent on the bore and must be observed acc. Table 2 or 3 . The Tables do not take temperatures over $+40^{\circ} \mathrm{C}$ into account. Please observe the guidelines below Tables 2 and 3.
- On shrink disk hubs (1.2), the transmittable torques on the shaft-hub connection exceed the maximum coupling values and are therefore not additionally specified.
The only exception to this is the shrink disk hub (1.2) Size 3 with bore $\varnothing 10$. In this case, only max. 41 Nm can be transmitted
These values are valid for the entire permitted temperature range from $-20^{\circ} \mathrm{C}$ up to $+100^{\circ} \mathrm{C}$.
- The recommended bore tolerances are to be produced using the position and tolerance width as references; at the same time, please keep to the shaft run-out and axial run-out tolerances of 0.03 mm (see Fig. 2).
$\square$ The shaft surfaces should be finely turned or ground ( $\mathrm{Ra}=0.8 \mu \mathrm{~m}$ ).
- The required yield point for the shafts used is at least 350 N/mm² (St60, St70, C45, C60).

Please observe the following when boring the shrink disk and radial clamping hubs (Items 1.1, 1.2):

- The shrink disk hubs (1.2) are generally delivered greased and pre-assembled. For production of the finish bore, the shrink disk (1.2.2) is de-installed and the shrink disk hub (1.2) is de-greased.
- Deburr the hubs (1.1/1.2), in particular in the area of the slots.
- Clean and re-grease the shrink disk hubs (1.2) in the contact area of the shrink disk or hub.
Permitted grease: Klüber Alltemp QNB 50


## Installation Position

ROBA ${ }^{\circledR}$-DS couplings are designed for horizontal installation. In case of vertical or inclined installation, on long sleeves (3) the sleeve's own weight must be supported with a vertical support. This vertical support including both centerings in the hub and in the sleeve is produced at the place of manufacture.


Fig. 2

## Hub Installation

The configuration of the different individual components can be seen in Fig. 1.

Guidelines on the Hub Installation of Types 95_.2_ (Shrink Disk Hubs) or 95_.4__ (Clamping Hubs):


- The torque transmission of the clamping hubs (1.1) or the shrink disk hubs (1.2) takes place using frictional locking
- The contact surfaces between the shrink disk (1.2.2) and the hub (1.2) are greased manufacturer-side.
- The hub bores and the shaft ends must be completely grease-free during installation. Greasy or oily bores or shafts do not transmit the maximum coupling torque.
- The shafts must not have a keyway.
- The clamping hubs (1.1) or the shrink disk hubs (1.2) must be completely relaxed. If necessary, loosen the screws (1.1.1 or 1.2.1) by several thread turns.

Hub Installation Type 95_.2__(Shrink Disk Hubs)
a) Mount the shrink disk hubs (1.2) onto the shafts using a suitable device and bring them into the correct position.
b) Tighten the tensioning screws (1.2.1) using a torque wrench evenly and one after the other in 3 to max. 6 tightening sequences to the torque stated in Table 1.
c) Check the tightening torque produced after 5 to 10 operating hours.

## For de-installation:

a) Loosen all tensioning screws (1.2.1) in several sequences by several thread turns.
b) Normally the hubs on the shaft are loosened by hand. If this is not possible, please proceed as follows: Remove the tensioning screws (1.2.1) and screw them into the tapped extracting holes in-between. Then, tighten them evenly and one after the other until the shrink disk (1.2.2) loosens.


Please take the axial space requirements for the tensioning screws to be screwed into the tapped extracting holes into account (length of the hexagon head screws Item 1.2.1 in Table 1).

Hub Installation Type 95_.4_ (Clamping Hubs)
a) Mount the clamping hubs (1.1) onto the shafts using a suitable device and bring them into the correct position.


The clamping screw (1.1.1) must be greased in the area of the thread. This is usually carried out manufacturer-side.
For greasing, please use NLGI Class 1.5 grease with a basic oil viscosity of $460 \mathrm{~mm}^{2} / \mathrm{s}$ at $40^{\circ} \mathrm{C}$, e.g. Mobilith SHC460. Should the grease layer be washed off, it must be re-greased customer-side.
b) Tighten the clamping screw (1.1.1) using a torque wrench to the torque stated in Table 1.
c) Check the tightening torque produced after 5 to 10 operating hours.

Hub Installation Type 951.8__ (Split Clamping Hubs)
a) Loosen the pre-assembled half-shells from the hubs (1.7), making sure that their correlation to the hub is maintained.


The cap screws (1.4.1) must be greased in the area of the thread. This is usually carried out manufacturer-side. For greasing, please use NLGI Class 1.5 grease with a basic oil viscosity of $460 \mathrm{~mm}^{2} / \mathrm{s}$ at $40^{\circ} \mathrm{C}$, e.g. Mobilith SHC460. Should the grease layer be washed off, it must be re-greased customer-side.
b) Place the coupling from above onto the shafts and pre-assemble it with the respective half-shells.
c) Tighten the cap screws (1.4.1) using a torque wrench to the torque stated in Table 1.
d) Tighten the cap screws (1.4.1) alternately and in several tightening sequences to the tightening torque stated in Table 1. Please make sure that the gap " $X$ " (Fig. 3) has the same size on both hub sides. If necessary, re-adjust it.
e) Check the tightening torque produced after 5 to 10 operating hours.


Fig. 3

## Installation and Operational Instructions for ROBA ${ }^{\circledR}$-DS couplings Type $95{ }_{1}^{0}$.

## Coupling Installation (Figs. 1 and 4)

The disk packs (2) are screwed together alternately with the hubs and the sleeve (3) or the connection plate (4) using lightly oiled cap screws (5 and 6) with washers (7).
Here, the tightening torque acc. Table 1 must be produced in several steps.
The cap screws (5 and 6) must be tightened in several steps to their full tightening torque acc. Table 1. Please see Table 4 for the respective tightening torques for each step.


In order to install the shrink disk hubs (1.2) with the respective connection elements, the shrink disk (1.2.2) must be unscrewed from the shrink disk hub (1.2).

Table 4

| Step | Tightening torque of the cap screws <br> (Items 5 and 6) |
| :---: | :---: |
| $\mathbf{1}$ | $30 \%$ of the nominal tightening torque |
| $\mathbf{2}$ | $60 \%$ of the nominal tightening torque |
| $\mathbf{3}$ | $100 \%$ of the nominal tightening torque |

The disk pack (2) must not under any circumstances be distorted when applying the pre-tension force.


The disk pack (2) is to be installed in such a way that the collar bushing
(Item 2a, Fig. 4) is combined with the corresponding tolerance bore in the respective hub, connection plate (4) or in the sleeve (3). Due to the high joining forces (caused by the transition tolerance) installation of the disk packs is only possible using the screw pretension force

For disk pack (2) disassembly, use suitable tools, e.g. screwdrivers on the right and left side of the collar bushing (2a) (Fig. 5).


Fig. 4


Fig. 5

## Coupling Alignment

Exact coupling alignment reduces the reaction forces and therefore increases the lifetime of the coupling and the shaft bearing.
In most of the applications, coupling alignment using a straight edge in two levels vertical to each other is sufficient. However, we recommend alignment of the coupling (of the shaft ends) using a dial gauge or laser on drives operating at very high speeds.
In order to prevent axial distortion of the disk packs, the dimension "S" (see Fig. 4 / page 9 and Table 1) must be maintained with aligned angular and radial shaft misalignments.

## Permitted Shaft Misalignments

ROBA $^{\circledR}$-DS single-jointed couplings (Type 950 $\qquad$
compensate for angular and axial shaft misalignments
ROBA ${ }^{\circledR}$-DS double-jointed couplings (Type 951 compensate for angular, axial and radial shaft misalignments (Fig. 7) without losing their backlash-free function. However, the permitted shaft misalignments indicated in Table 1 must not simultaneously reach their maximum value. If more than one kind of misalignment takes place simultaneously, they influence each other. This means that the permitted misalignment values are dependent on one another, see Fig. 6. The sum total of the actual misalignments in percent of the maximum value must not exceed $100 \%$ (see example and Fig. 6).


Fig. 6
$\Delta \mathrm{Ka}_{\mathrm{a}}$ [\%] Axial displacement

## Example:

ROBA $^{\circledR}$-DS, Size 10, Type 951.221
Axial displacement occurrence $\Delta \mathrm{K}_{\mathrm{a}}=0.36 \mathrm{~mm}$ equals $40 \%$ of the permitted maximum value $\Delta \mathrm{K}_{\mathrm{a}}=0.9 \mathrm{~mm}$
Angular misalignment occurrence in the disk pack $\Delta \mathrm{K}_{\mathrm{w}}=0.3^{\circ}$ equals $30 \%$ of the permitted maximum value $\Delta \mathrm{K}_{\mathrm{w}}=1^{\circ}$ $=>$ permitted radial misalignment $\Delta \mathrm{K}_{\mathrm{r}}=30 \%$ of the maximum value
$\Delta \mathrm{K}_{\mathrm{r}}=0.2 \mathrm{~mm}=>\Delta \mathrm{K}_{\mathrm{r}}=0.06 \mathrm{~mm}$


Axial displacement


Radial misalignment


Angular misalignment

Fig. 7

## Balancing the Coupling

In most applications, balancing the ROBA ${ }^{\circledR}$-DS coupling is not necessary
In general, the following points are crucial when deciding whether the coupling needs balancing:

- Circumferential speed of the coupling
- Length of the sleeves $S$ (Diagram 1)
- Required balance quality


## Diagram 1: Balancing the Couplings with Sleeve S (Special Length)



Smooth running of the machine is not only ensured by the coupling balance quality, but is also influenced by parameters such as rigidity and distance to the adjacent bearings as well as by the sensitivity and mass of the entire construction.
Diagram 1, therefore, only shows reference values as recommendations for balancing.
All parts of the ROBA ${ }^{\circledR}$-DS couplings, except for the sleeve $S$ pipe,
are machined on all sides, and therefore lie in the range G 6.3 acc. ISO DIN 1940 at medium speeds ( 1500 rpm ).
When ordering the coupling with a special sleeve, please always state the coupling operating speed.
If higher demands are placed on the balance quality, it is possible to balance individual parts or even the entire installed coupling (on request). However, for this option, the hubs must have a finish bore.

Diagram 2: Permitted Speeds (Bend-critical) for Sleeves S Type 951.__3


Example:
Size 6, sleeve length $\mathrm{H}_{\mathrm{S}}=1250 \mathrm{~mm}=>$ permitted speed 3000 rpm .

i
The coupling must be operated in the subcritical speed range.
Attention: When passing through the bend-critical speed (resonance), there is a danger of coupling destruction.

## Maintenance

ROBA $^{\circledR}$-DS couplings are mainly maintenance-free.
The following maintenance and inspection intervals are to be maintained:
1.) Visual inspection, inspection of the installation parameters (misalignment and tightening torques) and the coupling running behaviour before initial operation.
2.) Visual inspection, torsional backlash, inspection of the misalignment and the tightening torques, coupling running behaviour after 1000 h , at the latest after $\mathbf{3}$ months.
3.) If no irregularities or wear are found during the second maintenance and inspection interval, further inspection intervals can, with unchanged operating parameters, take place after 4000 operating hours or after maximum 12 months.

In extreme coupling ambient or operating conditions, the maintenance and inspection intervals should be shortened.

## Disposal

All steel components:

All aluminium components:
Non-ferrous metals (Code No. 160118)

## Malfunctions / Breakdowns

| Malfunction | Possible Causes | Solutions |  |
| :---: | :---: | :---: | :---: |
| Changes in running noise and / or vibration occurrence | Incorrect alignment, incorrect installation |  | Set the system out of operation <br> Find / resolve the cause of incorrect alignment <br> Check the coupling for wear |
|  | Loose connecting screws, fretting corrosion under the screw head and on the disk pack | $1)$ $2)$ $3)$ $4)$ | Set the system out of operation <br> Check the coupling parts and replace if damaged Tighten the connecting screws to the specified torque Check the alignment and correct if necessary |
|  | Tensioning and clamping screws for axial securement of the hubs are loose | 2) $3)$ 4) | Set the system out of operation <br> Check the coupling alignment <br> Tighten the tensioning and clamping screws for axial hub securement to the required torque and secure it against selfloosening using sealing lacquer <br> Check the coupling for wear |
| Disk pack breakage | $\begin{gathered} \text { Disk pack breakage } \\ \text { due to } \\ \text { high load impacts / overload } \end{gathered}$ | $2)$ 3) 4) | Set the system out of operation <br> Dismantle the coupling and remove the remainders of the disk packs <br> Check the coupling parts and replace if damaged <br> Find the cause of overload and remove it |
|  | Operating parameters are not appropriate for the coupling performance | 4) | Set the system out of operation <br> Check the operating parameters and select a suitable coupling (observe installation space) <br> Install a new coupling <br> Check the alignment |
|  | Incorrect operation of the system unit | 2) | Set the system out of operation <br> Dismantle the coupling and remove the remainders of the disk packs <br> Check the coupling parts and replace if damaged <br> Train and advise operating personnel |
| Disk packs / connecting screws cracks or breakage | Drive vibrations | $1)$ $2)$ 3) 4) 5) | Set the system out of operation <br> Dismantle the coupling and remove the remainders of the disk packs <br> Check the coupling parts and replace if damaged <br> Check the alignment and correct if necessary <br> Find the cause of vibration and remove it |

mayr ${ }^{\circledR}$ will take no responsibility or guarantee for replacement parts and accessories which have not been delivered by mayr ${ }^{\circledR}$, or for damage resulting from the use of these products.

